Technical Construction File (Test Report)

File No.: JAT-CE2292-0277

Revision Date:2020/10/20

Applicant/Holder: Anhui Toploong CNC Equipment Manufacturing Co., Ltd.

Address: 10 Hehuan Road, High-tech Zone, Hefei City, Anhui Province, China

Manufacturer: Anhui Toploong CNC Equipment Manufacturing Co., Ltd.

Product Type: Portable Flame and Plasma CNC Cutting Machine

Models: ZL1630

According to: MD 2006/42/EC



Test Result:	PASS
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Date: 21, 10, 2020 Tested by: Kelly Sun

Approved By: Jeff Zhang

TEST REPORT

EN ISO 12100:2010 EN 60204-1:2018

Safety of machinery - Electrical equipment of machines - Part 1: General requirements

Kelly Sun Tested by (Printed name and Signature).....: Kelly Sun

Date of issue....: Jeff Zhang
: 2020-10-21

Testing Laboratory Name...... Suzhou Standard Testing Technology Co., Ltd

Suzhou City, Jiangsu Province, China

Applicant's name...... Anhui Toploong CNC Equipment Manufacturing Co., Ltd.

Address 10 Hehuan Road, High-tech Zone, Hefei City, Anhui Province, China

Manufacturer's name...... Anhui Toploong CNC Equipment Manufacturing Co., Ltd.

Test specification:

Standard EN ISO 12100:2010 EN 60204-1:2018

Test procedure: IEC Procedure deviation...... N/A

Non-standard test method.....: N/A

Test Report Form No..... JAT-CE2292-0277

Test Report Form(s) Originator: SEV

Master TRF...... Dated 2020.10.12~2020.10.17

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Copy of marking plate

Portable Flame and Plasma CNC Cutting Machine

Model: ZL1630

Voltage(V):220V±10%、50Hz±1Hz

Power: 0.5 KW

Machine Span: 2050 MM

Length of machine tool guide: 6500 MM

Ambient Temperature: <u>-10°C~45°C</u>

Factory NO. YN2020072601 Production NO. 2020/09/26

Anhui Toploong CNC Equipment Manufacturing Co., Ltd.

Add: No.11 Jinghu Road, Xinzhuang Street, Yixing, Jiangsu, China

MADE IN CHINA

Test items particulars:	
1.Special conditions	
a)Is the machine to be used in the open air?	No
b)Will the machine use , process or produce explosive or	No
flammable material?	
c)Is the machine for use in potentially explosive or	No
flammable atmospheres	
d)Can the machine present special hazards when	No
producing or consuming certain materials	
e)Is the machine use for mines	No
2.Electrical supplies and related conditions	
a)Anticipated voltage fluctuations(if more than $\pm 10\%$)	Yes
b)Anticipated frequency fluctuations (if more than $\pm 2\%$)	No
c) Indicate possible future changes in electrical equipment	Yes
that will require an increase in the electrical supply	
requirements	
d)Specify voltage interruptions in supply if longer than	No
specified in Clause 4 where electrical equipment has to	
maintain operation under such conditions.	
3.Physical environment and operating conditions	
a) Electromagnetic environment	Industrial environment
Special conditions or requirements	No
b) Ambient temperature range	5 ℃~40℃
c) Humidity range	40%RH~90%RH
d) Altitude	<1000m
e) Special environmental conditions	No
f) Radiation	No

Г	T
g)Vibration, shock	Yes
h)Special installation and operation requirements	Yes
i)Transportation and storage	Yes
4.Incoming electrical supplies	
a)Nominal voltage(V)	a.c.220V/50Hz
Prospective short-circuit current at the point of supply to	No
the machine (kA r.m.s.)	
b)Type of power supply earthing	TN
c)Is the electrical equipment to be connected to a neutral	No
supply conductor?	
d)supply disconnecting device	YES
Is disconnection of the neutral conductor required?	No
Is a removable link for disconnecting the neutral required?	No
Type of supply disconnecting device to be provided	YES
5. protection against electric shock	
Test items particulars:	
a)For, which of the following classes of persons is access	Electrically skilled persons
to the interior of enclosures required during normal	
operation of the equipment?	
b)Are locks with removable keys to be provided for	Yes
securing the doors or covers?	
6. Protection of equipment	
a)Will the user or the supplier provide the overcurrent	Yes
protection of the supply conductors?	
Type and rating of overcurrent protective devices	See technical file
b)Largest(kW) three-phase a.c. motor that may be started	0.5 kw
direct-on-line	

c) May the number of motor overload detection devices be	No	
reduced?		
7. Operation		
For cableless control systems, specify the time delay	No	
before automatic machine shutdown is initiated in the		
absence of a valid signal.		
8. Operator interface and machine-mounted control de-	vices	
Special colour preferences:	No	
9. Controlgear		
Degree of protection of enclosures or special conditions:	>IP20	
10. Wiring practices		
Is there a specific method of identification to be used for	YES	
the conductors?(see 13.2.1)		
Туре	By a combination of numbers and	
	alphanumerics	
11. Accessories and lighting		
a)ls a particular type of socket-outlet required?	No	
b)Are the socket-outlets for maintenance to be provided	No	
with additional protection by the use of Residual Curret		
protective Devices(RCD)?		
c)Where the machine is equipped with local lighting:	No	
12. Marking, warnings and reference designations		
a)Functional identification	Yes	
b)Inscriptions/special markings	On electrical equipment, in English	
Mark of certification Yes, CE		
13. Technical documentation		
a) Technical documentation	English	
	•	

b)Size location and purpose of ducts, open cable trays or	Yes
cable supports to be provided by the user	
c)Indicate if special limitations on the size or weight which	Yes
affect the transport of a particular machine or controlgear	
assemblies to the installation site	
Test items particulars:	
-maximum dimensions:	3500*2100*430 MM
-maximum weight:	1
d)In the case of specially built machines, is a certificate of	No
operating tests with the loaded machine to be supplied?	
e)In the case of other machines, is a certificated of	Yes
operating type tests on a loaded prototype machine to be	
supplied?	
test case verdicts:	
test case does not apply to the test object:	N/A
- test object does meet the requirement:	P (Pass)
- test object does not meet the requirement:	F (Fail)
Testing:	
Date of receipt of test item 2020	-10-21
Date (s) of performance of tests: 2020	-10-12 to 2020-10-17
General remarks:	
The test results presented in this report relate only to the o	object tested.
This report shall not be reproduced, except in full, without	the written approval of the Issuing testing
laboratory.	
"(See Enclosure #)" refers to additional information append	ded to the report.
"(See appended table)" refers to a table appended to the r	eport.
Throughout this report a comma (point) is used as the dec	imal separator.

1. Risk assessment

This risk assessment report is based on the methods in the EN ISO 12100:2010 and EN ISO 14121-2 standards, and the 4 factors S-A-G-W have been used for evaluating the level of risks.

S: Severity of possible harm

- S1: Slight (normally reversible)
- S2: Serious (normally irreversible)
- S3: Cause a few men die
- S4: Calamity or cause many men die

A: Frequency any duration of exposure

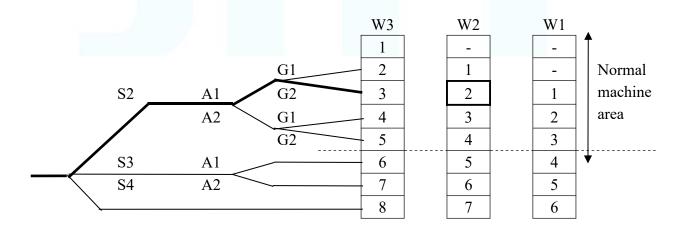
- A1: Seldom to very often
- A2: Frequent to continuous

G: Possibilities of avoidance

- G1: Possible
- G2: Impossible

W: Probability of occurrence of harm

- W1: Low
- W2: Medium
- W3: High



Solutions for the level of hazards

- 1: Protected by warning sign
- 2: Protected by guard and warning sign
- 3: Consider the other design, choose the best one, add both guard and warning sign
- 4: Consider another two design, choose the best one, add both guard and warning sign
- 5: Consider another three design, choose the best one, add both guard and warning sign

NO.	Hazards source	S	A	G	W	Level
	Mechanical hazards					
1.0-1	Mechanical hazards due to machine parts or work pieces					
1.0-2	Mechanical hazards due to accumulation of energy inside the					
	machinery					
1.1	Crushing	1	1	1	1	-
1.2	Shearing					
1.3	Cutting or severing					
1.4	Entanglement	1	1	1	1	_
1.5	Drawing-in or trapping	1	1	1	1	_
1.6	Impact	1	1	1	1	-
1.7	Stabbing or puncture					
1.8	Friction or abrasion					
1.9	High pressure fluid injection or ejection					
	Electrical hazards		•		•	
2.1	Contact with live parts	2	1	1	1	1
2.2	Contact with parts which have become live under faulty	2	,	,	,	1
	conditions	2	1	1	1	1
2.3	Approach to live part under high voltage					
2.4	Electrostatic phenomena					
2.5	Thermal radiation or other phenomena such as projection of					
	molten particles and chemical effects form short-circuits,					
	overloads etc.					
	Thermal hazards					
3.1	Burns, scalds and other injuries by a possible contact of					
	persons with objects or materials with an extreme high or					
3.1	low temperature, by flames or explosions and also by the					
	radiation of heat sources					
3.2	Damage to health by hot or cold working environment					
	Hazards generated by noise					
4.1	Hearing loss (deafness), other physiological disorders	1	1	1	1	-
4.2	Interference with speech communication, acoustic signals,	1	1	1	1	
	etc.	1	1	1	1	-
	Hazards generated by vibration					
5.1	Use of hand-help machines resulting in a variety of					
	neurological and vascular disorder					
5.2	Whole body vibration, particular when combined with poor					
	postures					
	Hazards generated by radiation					
6.1	Low frequency, radio frequency radiation, microwaves					
6.2	Infrared, visible and ultraviolet light					

6.3	X and gamma rays					
6.4	Alpha, beta rays, electron or ion beams, neutrons					
6.5	Lasers					
Н	azards generated by materials and substances processed or	used k	y the	mac	hiner	·y
7.1	Hazards from contact with or inhalation of harmful fluids,					
	gases, mists, fumes and dusts					
7.2	Fire and explosion hazard					
7.3	Biological and micro-biological (viral or bacterial) hazards					
Н	azards generated by neglecting ergonomic principles in made	chine (desig	n		
8.1	Unhealthy postures or excessive effort					
8.2	Inadequate consideration of hand-arm or foot-leg anatomy					
8.3	Neglected use of personal protection equipment					
8.4	Inadequate local lighting					
8.5	Mental overload or underload, stress					
8.6	Human error, human behavior	1	1	1	1	-
8.7	Inadequate design, location or identification of manual					
	controls					
	Combination of hazards		Г			1
9	Combination of hazards					
	Unexpected start-up, unexpected overrun/over	r-spee	d		П	ı
10.1	Failure/disorder of the control system	1	1	1	1	-
10.2	Restoration of energy on supply after an interruption					
10.3	External influences on electrical equipment					
10.4	Other external influences (gravity, wind, etc.)					
10.5	Errors in the software					
10.6	Error made by the operator (due to mismatch of machinery					
	with human characteristics and abilities, see 8.6)					
	Impossibility of stopping the machine in the best poss	ible co	nditi	ions		
11	Impossibility of stopping the machine in the best possible					
	conditions					
	Variations in the rotational speed of tool	S			I	I
12	Variations in the rotational speed of tools					
	Failure of the power supply					
13	Failure of the power supply					
	Failure of the control circuit	1 -	1 _		_	1
14	Failure of the control circuit	1	1	1	1	-
	Errors of fitting	T				
15	Errors of fitting	1	1	1	1	_
1.6	Break-up during operation	T				
16	Break-up during operation					
	Falling or ejected objects or fluids					

17	Falling or ejected objects or fluids	Т			T
- 1	Loss of stability / overturning of machiner	 rv			
18	Loss of stability / overturning of machinery	<u>, </u>			Τ
10	Slip, trip and fall of persons (related to machi	nerv)			
19	Slip, trip and fall of persons(related to machinery)				T
	Additional hazards, hazardous situations and hazardous eve	⊥ ents di	e to n	 nobility	
20	Relating to the traveling function				T
20.1	Movement when starting the engine				
20.2	Movement without a driver at the driving position				
20.3	Movement without all parts in a safe position				+
20.4	Excessive speed of pedestrian controlled machinery				+
20.5	Excessive oscillations when moving				+
20.6	Insufficient ability of machinery to be slowed down, stopped				+
_0.0	and immobilisated				
	Linked to the work position (including driving station)	on the	machi	ine ine	
21.1	Fall of persons during access to (or at/from) the work	T			T
	position				
21.2	Exhaust gases/lack of oxygen at the work position				
21.3	Fire (flammability of the cab, lack of extinguishing means)				
21.4	Mechanical hazards at the work position:				
	contact with the wheels;				
	rollover;				
	fall of objects, penetration by objects;				
	break-up of parts rotation at high speed;				
	contact of persons with machine parts or tools (pedestrian				
	controlled machines)				
21.5	Insufficient visibility form the work positions				
21.6	Inadequate lighting				
21.7	Inadequate seating				
21.8	Noise at the work position				
21.9	Vibration at the work position				
21.10	Insufficient means for evacuation/emergency exit				
	Due to the control system				
22.1	Inadequate location of manual controls				
22.2	Inadequate design of manual controls and their mode of				
	operation				\perp
	Form handling the machine (lack of stability	ty)			
23	Form handling the machine (lack of stability)		¯		
	Due to the power source and to the transmission	of pow	er		
24.1	Hazards form the engine and the batteries				

24.2	Hazards form the transmission of power between machines							
24.3	Hazards form coupling and towing							
	Form/to third persons	<u> </u>	1					
25.1	Unauthorized start-up/use							
25.2	Drift of a part away from its stopping position							
25.3	Lack or inadequacy of visual or acoustic warning means							
Insufficient instructions for the driver/operator								
26	Insufficient instructions for the driver/operator							
	Additional hazards, hazardous situations and hazardous ev	vents	due t	to lifti	ng			
27	Mechanical hazards and hazardous events							
27.1	Form load falls, collisions, machine tipping caused by:							
27.1.1	Lack of stability							
27.1.2	Uncontrolled loading-overloading-overturning moments							
	exceeded							
27.1.3	Uncontrolled amplitude of movements							
27.1.4	Unexpected/unintended movement of loads							
27.1.5	Inadequate holding devices/accessories							
27.1.6	Collision of more then one machine							
27.2	Form access of persons to load support							
27.3	Form derailment							
27.4	Form insufficient mechanical strength of parts							
27.5	Form inadequate selection of chains, ropes, lifting and							
	accessories and their inadequate integration into the machine							
27.6	Form inadequate selection of chains, ropes, lifting and							
	accessories and their inadequate integration into the machine							
27.7	Form lowering of the load under the control of friction brake							
27.8	Form abnormal conditions of							
	assembly/testing/use/maintenance							
27.9	Form the effect of load on persons (impact by load or							
	counterweight)							
	Electrical hazards							
28.1	Form lightning							
	Hazards generated by neglecting ergonomic pri	ncipl	es					
29.1	Insufficient visibility from the driving position							
Addit	ional hazards, hazardous and situations and hazardous eve	ents d	lue to	unde	rgrou	ınd		
	work		1					
30	Mechanical hazards and hazardous events due to:							
30.1	Lack of stability of powered roof supports							
30.2	Failing accelerator or brake control of machinery running on							
	rails							
30.3	Failing or lack of dead man's control of machinery running							

	on rails						
31	Restricted movem	nent of persons					
32	Fire and explosion	n					
33	Emission of dust,	gases etc.					
Additio	onal hazards, haza	ardous situations and hazardous events	due to	the li	fting	or n	noving
		of persons					
34	Mechanical hazar	ds and hazardous events due to:					
34.1	Inadequate mecha	nical strength-inadequate working					
	coefficients						
34.2	Failing of loading	control					
34.3	Failing of control	s in person carrier (function, priority)					
34.4	Over speed of per	son carrier					
35	Falling of person	from person carrier					
36	Falling or overtur	ning of person carrier					
37	Human error, hun	nan behavior					
NO.		Hazards source	S	A	G	W	Level
1.1	Crushing		1	1	1	1	-
Where	Near machine						
When	loading/unloading	g,maintenance					
		Improvement result					
		Method	S	A	G	W	Level
1. Affixir	ng suitable warning	g signs.	1	1	1	1	-
2. Only o	operation by traini	ng/authorized persons.					
3. Opera	ition of the machin	e shall conform to the instructions of the					
instructi	on manual.						
4. Check	and inspection ac	cording to the specified durations of the					
instructi	on manual.						
5. Provid	de guards.						

NO.	Hazards source	S	A	G	W	Level
1.4	Entanglement	1	1	1	1	
Where	Contact with roller of the machine					
When	during operation, inspection and maintenance of machine					
	Improvement result					
	Method				W	Level
1. Affixir	l. Affixing suitable warning signs.		1	1	1	1
2. Only o	operation by training/authorized persons.					
3. Opera	ation of the machine shall conform to the instructions of the					
instructi	on manual.					
4. Check	and inspection according to the specified durations of the					
instructi	on manual.					
5. Provid	de guards.					

NO.	Hazards source	S	A	G	W	Level	
1.5	Drawing-in or trapping	1	1	1	1	-	
Where	Contact with the conveyor of the machine				•		
When	during operation, inspection and maintenance of machine						
	Improvement result						
	Method	S	A	G	W	Level	
1. Affixi	ng suitable warning signs.	1	1	1	1	-	
2. Only	operation by training/authorized persons.						
3. Opera	tion of the machine shall conform to the instructions of the						
instructi	on manual.						
4. Check	and inspection according to the specified durations of the						
instructi	on manual.						
5. Provid	de guards.						

NO.	Hazards source	S	A	G	W	Level
1.6	Impact	1	1	1	1	-
Where	moving/rotating tool		•			
When	during operation, inspection and maintenance of machine					
	Improvement result					
	Method	S	A	G	W	Level
1. Affixi	ng suitable warning signs.	1	1	1	1	-
2. Only	operation by training/authorized persons.					
3. Opera	ation of the machine shall conform to the instructions of the					
instructi	on manual.					
4. Check	and inspection according to the specified durations of the					
instructi	on manual.					
5. Provi	de guards.					

NO.	Hazards source	S	A	G	W	Level
2.1	Contact with live parts	2	1	1	1	1
Where	contact with live parts or connections					
When	During commissioning, maintenance					
	Improvement result					
	Method	S	A	G	W	Level
1.Only o	peration by training/authorized persons.	1	1	1	1	-
_	tion of the machine shall conform to the instructions of the on manual.					
	and inspection according to the specified durations of the on manual.					
4. Using	safety components in accordance with those relevant					
internati	onal standards.					
5.Use of	warning label.					

NO.	Hazards source	S	A	G	W	Level
2.2	Contact with parts which have become live under faulty	2	1	1	1	1
	conditions					
Where	contact with live parts or connections					
When	during operation, inspection and maintenance of machine					
	Improvement result					
	Method	S	A	G	W	Level
1. Only	operation by training/authorized persons.	1	1	1	1	-
2. Opera	ation of the machine shall conform to the instructions of the					
instructi	on manual.					
3. Check	k and inspection according to the specified durations of the					
instructi	on manual.					
4. Using	safety components in accordance with those relevant					
internat	ional standards.					
5.Use of	warning label.					

NO.	Hazards source	S	A	G	W	Level
4.1	Hearing loss (deafness), other physiological disorders	1	1	1	1	-
Where	Near machine			•		
When	during operation, inspection and maintenance of machine					
	Improvement result					
	Method	S	A	G	W	Level
1. Only	operation by training/authorized persons.	1	1	1	1	-
2. Opera	ation of the machine shall conform to the instructions of the					
instructi	on manual.					

3. Check and inspection according to the specified durations of the			
instruction manual.			
4. Using safety components in accordance with those relevant			
international standards.			
5. Use of warning label.			

NO.	Hazards source	S	A	G	W	Level
4.2	Interference with speech communication, acoustic signals,	1	1	1	1	-
	etc.					
Where	Near machine					
When	during operation, inspection and maintenance of machine					
	Improvement result					
	Method	S	A	G	W	Level
1. Only	operation by training/authorized persons.	1	1	1	1	-
2.Use of	warning label.					
3.Use th	e PPE.					

NO.	Hazards source	S	A	G	W	Level
8.6	Human error, human behavior	1	1	1	1	_
Where	At load/unload, tool mounting positions					•
When	Reasonably foreseeable misuse, inadvertent operation of material and cutter handling and setting during loading/unlohandling.					
	Improvement result					
	Method	S	A	G	W	Level
1.Only a	uthorized person can use the machine.	1	1	1	1	-
2.Traini	ng before using this machine.					
3.Make	reference to the instruction manual before using this machine.					

NO.	Hazards source	S	A	G	W	Level
10.1	Failure/disorder of the control system	1	1	1	1	-
Where	the control system of the machine					
When	Mechanical hazards associated with selected machine moveme	nt du	ring.	settin	g,	
	cleaning					
	Improvement result					
	Method	S	A	G	W	Level
1. Only	authorized person can use the machine.	1	1	1	1	-
2. Mak	e reference to the instruction manual before using this					
machine						
3. Chec	ck before operation.					
4. Peri	odic maintenance.					

NO.	Hazards source	S	A	G	W	Level
14	Failure of the control circuit	1	1	1	1	-
Where	In the wireway					
When	Unexpected movements of machine during setting, cleaning or	mair	itenai	псе		
	Improvement result					
	Method	S	A	G	W	Level
1. Chec	cking before operation.	1	1	1	1	-
2. Mak	e reference to the instruction manual before operate this					
machine	2.					
3. Dail	y/periodic inspection and maintenance.					

NO.	Hazards source	S	A	G	W	Level
15	Errors of fitting	1	1	1	1	_
Where	At machine			•	•	
When	machine elements fail or swing unexpectedly during process co	ontro	l, tool	l mou	nting	.,
	maintenance					
	Improvement result					
	Method	S	A	G	W	Level
1. Only	authorized person can use the machine.	1	1	1	1	-
2.Make	reference to the instruction manual before using this machine.					
3.Check	before operation.					
4. Perio	dic maintenance.					

2. EN ISO 12100:2010

	EN ISO 12100:2010		
Clause	Requirement-Test	Result-Remark	Verdict

6	Risk reduction	P
6.1	General	P
	The objective of risk reduction can be achieved by the elimination of hazards, or by separately or simultaneously reducing each of the two elements that determine the associated risk: -severity of harm from the hazard under consideration; - probability of occurrence of that harm. All protective measures intended for reaching this objective shall be applied in the following sequence, referred to as the three-step method (see also Figures 1	P
6.2	and 2). Inherently safe design measures	P
6.2.1	General	P P
	Inherently safe design measures are the first and most Appropriate machine important step in the risk reduction process because protective measures inherent to the characteristics of the machine are likely to remain effective, whereas experience has shown that even well-designed safeguarding may fail or be violated and information for use may not be followed.	P
	Inherently safe design measures are achieved by avoiding hazards or reducing risks by a suitable choice design has been of design features of the machine itself and/or interaction between the exposed persons and the manufacturer. NOTE See 6.3 for safeguarding and complementary measures that can be used to achieve the risk reduction objectives in the case where inherently safe design measures are not sufficient (see 6.1 for the three-step method).	P
6.2.2	Consideration of geometrical factors and physical aspects	P
6.2.2.1	Geometrical factors	P
	Such factors include the following.	
	a) The form of machinery is designed to maximize direct Reducing blind spots visibility of the working areas and hazard zones from the control position — reducing blind spots, for example —	P

	EN ISO 12100:2010		
Clause	Requirement-Test	Result-Remark	Verdict
			1
	and choosing and locating means of indirect vision		
	where necessary (mirrors, etc.) so as to take into account		
	the characteristics of human vision, particularly when		
	safe operation requires permanent direct control by the		
	operator, for example:		
	-the travelling and working area of mobile machines;		
	-the zone of movement of lifted loads or of the carrier of		
	machinery for lifting persons;		
	-the area of contact of the tool of a hand-held or		
	hand-guided machine with the material being worked.		
	The design of the machine shall be such that, from the		
	main control position, the operator is able to ensure that		
	there are no exposed persons in the danger zones.		
	b) The form and the relative location of the mechanical	By increasing the	P
	components parts: for instance, crushing and shearing	minimum gap	
	hazards are avoided by increasing the minimum gap	between the moving	
	between the moving parts, such that the part of the body	parts or by reducing	
	under consideration can enter the gap safely, or by	the gap.	
	reducing the gap so that no part of the body can enter it		
	(see ISO 13854 and ISO 13857).		
	c) Avoiding sharp edges and corners, protruding parts:	No sharp edges, no	P
	in so far as their purpose allows, accessible parts of the	sharp angles, no	
	machinery shall have no sharp edges, no sharp angles,	rough surfaces, no	
	no rough surfaces, no protruding parts likely to cause	protruding parts.	
	injury, and no openings which can "trap" parts of the		
	body or clothing. In particular, sheet metal edges shall		
	be deburred, flanged or trimmed, and open ends of tubes		
	which can cause a "trap" shall be capped.		
	d) The form of the machine is designed so as to achieve	Suitable working	P
	a suitable working position and provide accessible		
	manual controls (actuators).	manual controls.	
6.2.2.2	Physical aspects		P
	Such aspects include the following:		_
	a) limiting the actuating force to a sufficiently low value	The actuating force	P
	so that the actuated part does not generate a mechanical	has been limited to be	
	hazard;	a sufficiently low	
	, ,	value.	
	b)limiting the mass and/or velocity of the movable	The mass of the tool	P
	elements, and hence their kinetic energy;	has been limited.	1

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Clause	Requirement-Test	Result-Remark	Verdict
	c) limiting the emissions by acting on the characteristics		P
	of the source using measures for reducing:		
	1) noise emission at source (see ISO/TR 11688-1),		
	2) the emission of vibration at source, such as		
	redistribution or addition of mass and changes of process		
	parameters [for example, frequency and/or amplitude of		
	movements (for hand-held and hand-guided machinery,		
	see CR 1030-1)],		
	3) the emission of hazardous substances, including the		
	use of less hazardous substances or dust-reducing		
	processes (granules instead of powders, milling instead of grinding), and		
	4) radiation emissions, including, for example, avoiding		
	the use of hazardous radiation sources, limiting the		
	power of radiation to the lowest level sufficient for the		
	proper functioning of the machine, designing the source		
	so that the beam is concentrated on the target, increasing		
	the distance between the source and the operator or		
	providing for remote operation of the machinery		
	[measures for reducing emission of non-ionizing		
	radiation are given in 6.3.4.5 (see also EN 12198-1 and		
	EN 12198-3)].		
6.2.3	Taking into account the general technical knowledge		P
	regarding machine design		
	This general technical knowledge can be derived from		
	technical specifications for design (e.g. standards, design		
	codes, calculation rules). These should be used to cover:		
	a) mechanical stresses such as	The appropriate	P
	- stress limitation by implementation of correct	technical knowledge	
	calculation, construction and fastening methods as	of mechanical has	
	regards, e.g. bolted assemblies, welded assemblies	been taken into	
	- stress limitation by overload prevention, (e.g. "fusible"	account.	
	plugs, pressure-limiting valve, breakage points,		
	torque-limiting devices);		
	- avoiding fatigue in elements under variable stresses		
	(notably cyclic stresses);		
	- static and dynamic balancing of rotating elements;		

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Clause	Requirement-Test	Result-Remark	Verdict
	b) materials and their properties such as	The materials have	P
	- resistance to corrosion, ageing, abrasion and wear;	been treated by	
	- hardness, ductility, brittleness;	appropriate methods.	
	- homogeneity;		
	- toxicity; - flammability.		
	-		
	c) emission values for :		P
	- noise; - vibration;		
	- hazardous substances;		
	- radiation.		
	When the reliability of particular components or		P
	assemblies is critical for safety (e.g. ropes, chains, lifting		
	accessories for lifting loads or persons), stress values		
	shall be multiplied by appropriate working coefficients.	during design and	
6.2.4		calculation.	
6.2.4	Choice of an appropriate technology		N
	One or more hazards can be eliminated or risks reduced		-
	by the choice of the technology to be used in certain		
	applications, e.g. :		
	a) on machines intended for use in explosive		N
	atmospheres:		
	- fully pneumatic or hydraulic control system and		
	machine actuators; - "intrinsically safe" electrical equipment (see IEC		
	60079-11)		
	b) for particular products to be processed such as a		N
	solvent: equipment assuring that the temperature will		11
	remain far below the flash point.		
	c) alternative equipment to avoid high noise level, e.g.:		N
	- electrical instead of pneumatic equipment		1
	- in certain conditions, water cutting instead of		
	mechanical equipment.		
6.2.5	Applying the principle of the positive mechanical action		P
	Positive mechanical action is achieved when a moving		P
	mechanical component inevitably moves another		
	component along with it, either by direct contact or via		
	rigid elements. An example of this is positive opening		
	operation of switching devices in an electrical circuit		

(see IEC 60947-5-1 and ISO 14119). Provisions for stability Machines shall be designed to have sufficient stability to allow them to be used safely in their specified conditions of use. Factors to be taken into account include - geometry of the base; The factor has been taken into account during design. - weight distribution, including loading; The factor has been taken into account during design. - dynamic forces due to movements of parts of the machine, of the machine itself, or of elements held by taken into account during design. - vibration The factor has been taken into account during design. The factor has been taken into account during design. The factor has been taken into account during design. The factor has been taken into account during design. - oscillations of the centre of gravity; The factor has been taken into account during design. - characteristics of the supporting surface in case of traveling or installation on different sites (e.g. ground conditions, slope); - external forces (e.g. wind pressure, manual forces) Stability shall be considered in all phases of the life of the machine, including handling, traveling, installation, taken into account during design. The factor has been taken into account during design. The factor has been taken into account during design. The factor has been taken into account during design. The factor has been taken into account during design. Other protective measures for stability relevant to safeguarding are given in 6.3.2.6 6.2.7 Provision for maintainability When designing a machine, the following maintainability factors shall be taken into account: - accessibility, taking into account the environment and These factors have	EN ISO 12100:2010			
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- accessibility, taking into account the environment and These factors have P				
		-	These factors have	Р
		the human body measurements, including the	been taken into	

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Clause	Requirement-Test	Result-Remark	Verdict
	dimensions of the working clothes and tools used;	account during	
		design.	
	- ease of handling, taking into account human	The factor has been	P
	capabilities;	taken into account	
		during design.	
	- limitation of the number of special tools and	The factor has been	P
	equipment;	taken into account	
		during design.	
6.2.8	Observing ergonomic principles		P
	Ergonomic principles shall be taken into account in	Appropriate	P
	designing machinery to reduce mental or physical stress	ergonomic principles	
	and strain of the operator.	have been taken into	
		account in designing	
		machinery.	
	These principles shall be considered when allocating	These principles have	P
	functions to operator and machine (degree of	been taken into	
	automation) in the basic design.	account during	
		allocating functions to	
		operator and machine.	
	Account shall be taken of body sizes likely to be found	All these factors have	P
	in the intended user population, strengths and postures,		
	movement amplitudes, frequency of cyclic actions (see	account during	
	ISO 10075 and ISO 10075-2)	design.	
	All elements of the "operator-machine" interface such as	All arrangement and	P
	controls, signaling or data display elements, shall be	design of manual	
	designed to be easily understood so that clear and	controls have been	
	unambiguous interaction between the operator and the		
	machine is possible.(see EN 614-1, ISO 6385, EN 13861	compliance with.	
	and IEC 61310-1)		
	Designer's attention is especially drawn to following		-
	ergonomic aspects of machine design		
	a) Avoiding stressful postures and movements during		P
	use of the machine (e.g. by providing facilities to adjust		
	the machine to suit the various operators).	use of the machine	
		have been avoided.	
	b) Designing machines, and more especially hand-held		P
	and mobile machines to enable them to be operated	_	
	easily taking into account human effort, actuation of	human strength and	
	controls and hand, arm and leg anatomy.	convenient	

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		movement.	
	c) Limit as far as possible noise, vibration and thermal	This machine has	P
	effects such as extreme temperatures.	been designed with	
		low noise, vibration.	
	d) Avoid linking the operator's working rhythm to an	This situation has	P
	automatic succession of cycles.	been avoided.	
	e) Select, locate and identify manual controls (actuators)		-
	so that		
	- they are clearly visible and identifiable and	Clearly visible and	P
	appropriately marked where necessary (see6.4.4)	appropriately marked	
	- they can be safely operated without hesitation or loss	Standard layout of	P
	of time and without ambiguity (e.g. a standard layout of	controls.	
	controls reduces the possibility of error when an	See the photos.	
	operator changes from a machine to another one of		
	similar type having the same pattern of operation)		
	- their location(for push-buttons) and their movement		P
	(for levers and handwheels) are consistent with their		
	effect (see IEC 61310-3)		
	- their operation cannot cause additional risk		P
	Where a control is designed and constructed to perform		N
	several different actions, namely where there is no	1	
	one-to-one correspondence (e.g. keyboards), the action		
	to be performed shall be clearly displayed and subject to		
	confirmation where necessary.		_
	Controls shall be so arranged that their layout, travel and	•	P
	resistance to operation are compatible with the action to	ergonomic principles	
	be performed, taking account of ergonomic principles.		D
	Constraints due to the necessary or foreseeable use of		P
	personal protective equipment(such as footwear,		
	gloves)shall be taken into account. f) Select, design and locate indicators, dials and visual		
	display units so that		-
	- they fit within the parameters and characteristics of		P
	human perception		r
	- information displayed can be detected, identified and	All the information	P
	interpreted conveniently, i.e. long lasting, distinct,		1
	unambiguous and understandable with respect to the		
	operator's requirements and the intended use;	with this requirement.	
	- the operator is able to perceive them form the control		P
	The state of the s	1	1

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	position		
6.2.9	Preventing electrical hazard		P
	For the design of the electrical equipment of machines	See the test report of	P
	EN 60204-1 gives general provisions, especially in	EN 60204-1	
	clause 6 for protection against electric shock.		
	For requirements related to specific machines, see		N
	corresponding IEC standards (e.g. series of IEC 61029,		
	IEC 60745, IEC 60335).		
6.2.10	Preventing and hydraulic hazards		N
	Pneumatic and hydraulic equipment of machinery shall		-
	be designed so that:		
	- the maximum rated pressure cannot be exceeded in the		N
	circuits (e.g. by means of pressure limiting devices)		
	- no hazard results from pressure surges or rises,		N
	pressure losses or drops or losses of vacuum;		
	- no hazardous fluid jet or sudden hazardous movement		N
	of the hose (whiplash)results from leakage or component		
	failures;		
	- air receivers, air reservoirs or similar vessels (e.g. in		N
	gas loaded accumulators) comply with the design rules		
	for these elements;		
	- air elements of the equipment, and especially pipes and		N
	hoses, be protected against harmful external effects;		
	- as far as possible, reservoirs and similar vessels (e.g. in		N
	gas loaded accumulators) are automatically		
	depressurized when isolating the machine from its		
	power supply (see 6.3.5.4) and, if it is not possible,		
	means are provided for their isolation, local		
	depressurizing and pressure indication (see also ISO		
	14118:2000, clause 5)		
	- all elements which remain under pressure after		N
	isolation of the machine from its power supply be		
	provided with clearly identified exhaust devices, and a		
	warning label drawing attention to the necessity of		
	depressurizing those elements before any setting or		
	maintenance activity on the machine.		
	See also ISO 4413 and ISO4414		
6.2.11	Applying inherently safe design measures to control		P
	system		

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6.2.11.1	General		P
	The design measures of the control system shall be	Inherently safe design	P
	chosen so that their safety-related performance provides		
	a sufficient amount of risk reduction (see ISO 13849-1	system have applied.	
	or IEC 62061)		
	The correct design of machine control systems can avoid	_	P
		measures to control	
	behaviour.	system have applied.	
	Typical causes of hazardous machine behavior are:		-
	- an unsuitable design or modification (accidental or	No this kind of hazard	N
	deliberate) of the control system logic;	in this machine	
	- a temporary or permanent defect or a failure of one or		N
	several components of the control system;		
	- a variation or a failure in the power supply of the	No this kind of hazard	N
		in this machine	
	- inappropriate selection, design and location of the	No this kind of hazard	N
	control devices;	in this machine	
	Typical examples of hazardous machine behaviour are:		-
	- unintended/unexpected start-up(see ISO 14118)	No this kind of hazard	N
		in this machine	
	- uncontrolled speed change;	Speed monitor	N
	- failure to stop moving parts;	Emergency stop	N
		devices	
	- dropping or ejection of a mobile part of the machine or		P
	of a workpiece clamped by the machine;		
	- machine action resulting from inhibition (defeating or		N
	failure) of protective devices	in this machine	
	In order to prevent hazardous machine behaviour and to		P
	achieve safety functions, the design of control systems		
	shall comply with the principles and methods presented		
	in this subclause 6.2.11 and in 6.2.12.	~ 1	
	These principles and methods shall be applied singly or	See the test report of	P
	in combination as appropriate to the circumstances (see	EN 60204-1	
	ISO 13849-1 and EN 60204-1 and IEC 62061).	T1	D
	Control systems shall be designed to enable the operator		P
	to interact with the machine safely and easily; this		
	requires one or several of the following solutions;	safely and easily.	- D
	- systematic analysis of start and stop conditions;	Systematic analysis	P

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have been applied.	
- provision for specific operating modes (e.g. start-up Enough provisions	P
after normal stop, restart after cycle interruption or after have been provided	l .
emergency stop, removal of the workpieces contained in	
the machine, operation of a part of the machine in case	
of a failure of a machine element)	
- clear display of the faults;	P
- measures to prevent accidental generation of Main switch with	P
unexpected start commands (e.g. shrouded start device) lock and related	
likely to cause dangerous machine behaviour (see ISO devices are provide	d.
14118:2000, figure 1)	
- maintained stop commands(e.g. interlock) to prevent This requirement is	P
restarting that could result in dangerous machine complied with.	
behaviour (see ISO 14118:2000, figure 1)	
An assembly of machines may be divided into several	P
zones for emergency stopping, for stopping as a result of	
protective devices and/or for isolation and energy	
dissipation.	
The different zones shall be clearly defined and it shall	P
be obvious which parts of the machine belong to which	
zone.	
Likewise it shall be obvious which control devices (e.g.	P
emergency stop devices, supply disconnecting	
devices)and/or protective devices belong to which zone.	
The interfaces between zones shall be designed such that	P
no function in one zone creates hazards in another zone	
which has been stopped for an intervention.	
Control systems shall be designed to limit the The max. speed	P
movements of parts of the machinery, the machine itself,	
or workpieces and/or loads held by the machinery, to the	
safe design parameters(e.g. range, speed, acceleration,	
deceleration, load capacity). Allowance shall be made	
for dynamic effects (e.g. the swinging of loads).	
For example:	_
- the traveling speed of mobile pedestrian controlled	N
machinery other than remote-controlled shall be	
compatible with walking speed.	
- the range, speed, acceleration and deceleration of	N
movements of the person-carrier and carrying vehicle for	1

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	lifting persons shall be limited to non-hazardous values,	
	taking into account the total reaction time of the operator	
	and the machine.	
	- the range of movements of parts of machinery for	P
	lifting loads shall be kept within specified limits.	
	When machinery is designed to use synchronously	N
	different elements which can also be used independently	
	the control system shall be designed to prevent risks due	
	to lack of synchronization.	
6.2.11.2	Starting of internal power source/switching on an	P
	external power supply	
	The starting of an internal power source or switching-on Not result in the	P
	of an external power supply shall not result in a starting of working	
	hazardous situation. For example: parts of a machine	
	-starting the internal combustion engine shall not lead to	
	movement of a mobile machine;	
	-connection to mains electricity supply shall not result in	
	the starting of working parts of a machine. See EN	
	60204-1:2006, 7.5 (see also Annexes A and B).	
6.2.11.3	Starting/stopping of a mechanism	P
	The primary action for starting or accelerating the This requirement has	P
	movement of a mechanism should be performed by been taken into	
	application or increase of voltage or fluid pressure, or, if account during	
	binary logic elements are considered, by passage from design.	
	state 0 to state 1(if state 1 represents the highest energy	
	state)	
	The primary action for stopping or slowing down should The type of stopping	P
	be performed by removal or reduction of voltage or fluid of this machine	
	pressure, or, if binary logic elements are considered, by belongs to state 1 and	
	passage from state 1 to state 0 (if state 1 represents the state 0.	
	highest energy state).	
	When, in order for the operator to maintain permanent No such situation	N
	control of deceleration, this principle is not observed exist.	
	(e.g. a hydraulic braking device of a self-propelled	
	mobile machine), the machine shall be equipped with a	
	means of slowing and stopping in case of failure of the	
	main braking system	
6.2.11.4	Restart after power interruption	P
	If it may generate a hazard, the spontaneous restart of a A self-maintained	P

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Clause	Requirement-Test	Result-Remark	Verdict
	machine when it is re-energized after power interruption		
	shall be prevented (e.g. by use of a self-maintained relay,		
	contactor or valve).		
6.2.11.5	Interruption of power supply		P
	Machinery shall be designed to prevent hazardous		P
	situations resulting from interruption or excessive		
	fluctuation of the power supply. At least the following		
	requirements shall be met:		
	- the stopping function of the machinery shall remain;		P
	- all devices whose permanent operation is required for		P
	safety shall operation an effective way to maintain safety		
	(e.g. locking, clamping devices, cooling or heating		
	devices, power-assisted steering of self-propelled mobile		
	machinery);		
	- parts of machinery or workpieces and/or loads held by		N
	machinery which are liable to move as a result of		
	potential energy shall be retained for the time necessary		
	to allow them to be safely lowered.		
6.2.11.6	Use of automatic monitoring		P
	Automatic monitoring is intended to ensure that a safety		P
	function(s) implemented by a protective measure do(es)		
	not fail to be performed if the ability of a component or		
	an element to perform its function is diminished, or if		
	the process conditions are changed in such a way that		
	hazards are generated.		
	Automatic monitoring either detects a fault immediately		P
	or carries out periodic checks so that a fault is detected		
	before the next demand upon the safety function.		
	In either case, the protective measure can be initiated		P
	immediately or delayed until a specific event occurs		
	(e.g. the beginning of the machine cycle.) The protective		
	measures may be , e.g.:		
	- the stopping of the hazardous process;		P
	- preventing the re-start of this process after the first stop		
	following the failure;		
	- the triggering of an alarm		N
6.2.11.7	Safety functions implemented by programmable		P
	electronic control systems		
6.2.11.7.1	General		P

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Clause	Requirement-Test	Result-Remark	Verdict
	A control system including programmable electronic		P
	equipment (e.g. programmable controllers) can be used		
	to implement safety functions t machinery.		
	Where a programmable electronic control system is used		P
	it is necessary to consider its performance requirements		
	in relation to the requirements for the safety functions.		
	The design of the programmable electronic control	Comply with the	P
	system shall be such that the probability of random	requirement	
	hardware failures and the likelihood of systematic		
	failures that can adversely affect the performance of the		
	safety-related control function(s) are sufficiently low.		
	Where a programmable electronic control system		P
	performs a monitoring function, the system behaviour on		
	detection of a fault shall be considered (see also IEC		
	61508 series for further guidance)		
	The programmable electronic control system should be	Comply with the	P
	installed and validated to ensure that the specified	requirement	
	performance (e.g. safety integrity level (SIL) in IEC		
	61508 series) for each safety function has been achieved.		
	Validation comprises testing an analysis (e.g. static,		P
	dynamic or failure analysis) to show that all parts		
	interact correctly to perform the safety function and that		
	unintended functions do not occur.		
6.2.11.7.2	Hardware aspects		P
	The hardware (including e.g. sensors, actuators, logic	Logic solvers	P
	solvers) shall be selected (and/or designed) and installed		
	to meet both the functional and performance		
	requirements of the safety function(s) to be performed,		
	in particular, by means of:		
	- architectural constraints (e.g. the configuration of the		P
	system, its ability to tolerate faults, its behaviour on		
	detection of a fault);		
	- selecting (and/or designing) equipment and devices		P
	with an appropriate probability of dangerous random		
	hardware failure;		
	-Incorporating measures and techniques within the		P
	hardware to avoid systematic failures and control		_
	systematic faults.		
6.2.11.7.3	Software aspects		P
0.2.11./.3	Bottware aspects		1

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Clause	Requirement-Test Result-Remark	Verdict
	The software (including internal operating software (or Satisfy the	P
	system software) and application software) shall be performance	
	designed so as to satisfy the performance specification specification for the	
	for the safety functions (see also IEC 61508-3) safety functions	
	Application software	-
	Application software should not be re-programmable by	P
	the user.	
	This may be achieved by use of embedded software in a	N
	non re-programmable memory (e.g. micro-controller,	
	application specific integrated circuit (ASIC)	
	When the application requires reprogramming by the	N
	user, the access o the software dealing with safety	
	functions should be restricted e.g. by :	
	- locks;	
6.2.11.0	- passwords for the authorized persons	_
6.2.11.8	Principles relating to manual control	P
	a) Manual control devices shall be designed and located See the photo.	P
	according to the relevant ergonomic principles given in	
	6.2.8	
	b) A stop control device shall be placed near each start A stop control device	P
	control device. Where the start/stop function is has been placed near	
1	performed by means of a hold-to-run control, a separate each start control	
	stop control device shall be provided when a risk can device.	
	result from the hold-to-run control device failing to	
	deliver a stop command when released. c) Manual controls shall be located out of reach of the Manual controls have	P
	danger zones (see IEC 61310-3), except for certain been located out of	Г
	controls where, of necessity, they are located within a reach of the danger	
	danger zone, such as emergency stop or teach pendant. zones.	
	d) Whenever possible, control devices and control The operator is able	P
	positions shall be located so that the operator is able to to observe the	1
	observe the working area or hazard zone. working area or	
	hazard zone.	
	The driver of a ride-on mobile machine shall be able to Not a ride-on mobile	N
	actuate all control devices required to operate the machine	
	machine from the driving position, except for functions	
	which can be controlled more safely from other	
	positions.	
	1	1

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Clause	Requirement-Test	Result-Remark	Verdict
	On machinery intended for lifting persons, controls for	Not for lifting	N
	lifting and lowering and, if appropriate, for moving the	persons.	
	carrier, shall generally be located in the carrier.		
	If safe operation requires controls to be situated outside		
	the carrier, the operator in the carrier shall be provided		
	with the means of preventing hazardous movements.		
	e) if it is possible to start the same hazardous element by	Only one control.	N
	means of several controls, the control circuit shall be so		
	arranged that only one control is effective at a given		
	time. This applies especially to machines which can be		
	manually controlled by means among others of a		
	portable control unit (teach pendant, for instance), with		
	which the operator may enter danger zones.		
	f) Control actuators shall be designed or guarded so that		P
	their effect, where a risk is involved, cannot occur		
	without intentional operation (see ISO 9355-1 and ISO		
	447)		
	g) For machine functions whose safe operation depends		N
	on permanent, direct control by the operator, measures		
	shall be taken to ensure the presence of the operator at		
	the control position, e.g. by the design and location of		
	control devices.		
	h) For cableless control an automatic stop shall be		P
	performed when correct control signals are not received,		
	including loss of communication (see EN 60204-1)		
6.2.11.9	Control mode for setting, teaching, process changeover,		P
	fault-finding, cleaning or maintenance		
	Where, for setting, teaching, process changeover,		N
	fault-finding, cleaning or maintenance of machinery, a		
	guard has to displaced or removed and/or a protective		
	device has to be disabled, and where it is necessary for		
	the purpose of these operations for the machinery or part		
	of the machinery to be put in operation, safety of the		
	operator shall be achieved using a specific control mode		
	which simultaneously:		
	- disables all other control modes;		N
	- permits operation of the hazardous elements only by		N
	continuous actuation of an enabling device, a		

	4.
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hold-to-run control device or a two-hand control device;	
- permits operation of the hazardous elements only in	N
reduced risk conditions (e.g. reduced speed, reduced	
power/force, step-by-step operation, e.g. with a limited	
movement control device)	
	V
voluntary or involuntary action on the machine's sensors.	
This control mode shall be associated with one or more	-
of following measures:	
	P
possible.	
The second secon	P
operator;	_
1 / 1 /	P
controls allowing sight of the controlled elements.(see	
EN 60204-1:2006, 9.2.4)	
1 C	P
	P
use in several control or operating modes requiring selector which can be	
different protective measures and/or work procedures locked in each	
(e.g. to allow for adjustment, setting, maintenance, position. inspection), it shall be fitted with a mode selector which	
can be locked in each position.	
	P
and shall exclusively allow one control or operating	
mode.	
	P
which restricts the use of certain functions of the	
machinery to certain categories of operators (e.g. access	
codes for certain numerically controlled functions).	
	P
compatibility (EMC)	
	P
60204-1, and IEC 61000-6 series.	
6.2.11.12 Provision of diagnostic systems to aid fault-finding	P
Diagnostic systems to aid fault finding should be	P
included in the control system so that there is no need to	
disable any protective measures.	

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6.2.12	Minimizing the probability of failure of safety functions	P
6.2.12.1	General	P
	Safety of machinery is not only dependent on the	P
	reliability of the control systems but also on the	
	reliability of all parts of the machine. The continued	
	operation of the safety functions is essential for the safe	
	use of the machine. This can be achieved by :	
6.2.12.2	Use of reliable components	P
	"Reliable components" means components which are Reliable components	P
	capable of withstanding all disturbances and stresses have been used.	
	associated with the usage of the equipment in the	
	conditions of intended use (including the environmental	
	conditions), for the period of time or the number of	
	operations fixed for the use, with a low probability of	
	failures generating a hazardous malfunctioning of the	
	machine. Components shall be selected taking into	
	account all factors mentioned above(see also 6.213)	
6.2.12.3	Use of "oriented failure mode" components	P
	"Oriented failure mode" components or systems are	P
	those in which the predominant failure mode is known	
	in advance and which can be used so that such a failure	
	leads to a non-hazardous alteration of the machine	
	function.	
	The use of such components should always be	P
	considered, particularly in cases where redundancy is	
	(see 6.2.12.4) not employed.	
6.2.12.4	Duplication (or redundancy) of components or	-
	subsystems	
	In the design of safety-related parts of the machine, No duplication (or	N
	duplication (or redundancy) of components may be used redundancy) of	
	so that, if one component fails, another component (or components	
	other components) continue(s) to perform its (their)	
	function, thereby ensuring that the safety function	
	remains available.	
	In order to allow the proper action to be initiated, Be preferably	P
	component failure shall be preferably detected by detected by automatic	
	automatic monitoring (see 6.2.11.6) or in some monitoring	
	circumstances by regular inspection,	

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	provided that the inspection interval is shorter than the		P
	expected lifetime of the components.		
	Diversity of design and/or technology can be used to		P
	avoid common cause failures (e.g. from electromagnetic		
6.2.12	disturbance) or common mode failures.		
6.2.13	Limiting exposure to hazards through reliability of equipment		
	Increased reliability of all component parts of machinery	This requirement is	P
	reduces the frequency of incidents requiring	complied with.	
	rectification, thereby reducing exposure to hazards.		
	This applies to power systems (operative part) as well as	This requirement is	P
	to control systems, to safety functions as well as to other functions of machinery.	complied with.	
	Safety-critical components (as e.g. certain sensors) with	Safety-critical	P
		components are used.	
	The elements of guards and of protective services shall		P
	be particularly reliable, as their failure can expose		
	persons to hazards, and also as poor reliability would		
	encourage attempts to defeat them.		
6.2.14	Limiting exposure to hazards through mechanization or		P
	automation of loading(feeding) /unloading (removal)		
	operations		
	Mechanization and automation of machine		P
	loading/unloading operations and more generally of		
	handling operations (of workpieces, materials,		
	substances) limit the risk generated by these operations		
	by reducing the exposure of persons to hazards at the		
	operating points.		2.7
	Automation can be achieved e.g. by robots, handling		N
	devices, transfer mechanisms, air blast equipment.		NT
	Mechanization can be achieved, e.g. by feeding slides,		N
	push rods, hand-operated indexing tables.		N
	While automatic feeding and removal devices have		N
	much to offer in preventing accidents to machine		
	operators, they can create danger when any faults are being rectified.		
	Care shall be taken to ensure that the use of these		N
	devices does not introduce further hazards (e.g. trapping,		1.4
	at the same and the meroduce further hazards (e.g. happing,		

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		T
	crushing) between the devices and parts of the machine	
	or workpieces/materials being processed.	
	Suitable safeguards (see 6.3) shall be provided if this	N
	cannot be ensured.	
	Automatic feeding and removal devices with their own Comply with the	P
	control systems and the control systems of the associated requirement	
	machine shall be interconnected after thoroughly	
	studying how all safety functions are performed in all	
	control and operation modes of the whole equipment.	
6.2.15	Limiting exposure to hazards through location of the	N
	setting and maintenance points outside of danger zones.	
	The need for access to danger zones shall be minimized	N
	by locating maintenance, lubrication and setting points	
	outside these zones.	
6.3	Safeguarding and complementary protective measures	P
6.3.1	General	P
	Guards and protective devices shall be used to protect Appropriate guards	P
	persons whenever inherently safe design does not and protective devices	
	reasonably make it possible either to remove hazards or have been used to	
	to sufficiently reduce risks. Complementary protective protect persons	
	measures involving additional equipment (e.g.	
	emergency stop equipment) may have to be	
	implemented.	
	Certain safeguards may be used to avoid exposure to fixed guard is used.	P
	more than one hazard (e.g. a fixed guard preventing	
	access to a zone where a mechanical hazard is present	
	being used to reduce noise level and collect toxic	
	emissions)	
6.3.2	Selection and implementation of guards and protective	P
	devices	
6.3.2.1	General -	
	This subclause gives guidelines for the selection and the Please see the related	P
	implementation of guards and protective devices the clause.	
	primary purpose of which is to protect persons against	
	hazard generated by moving parts, according to the	
	nature of those parts (see figure 4) and to the need for	
	access to the danger zone(s).	
	The exact choice of a safeguard for a particular machine	P

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	shall be made on the basis of the risk assessment for that machine.		
	In selecting an appropriate safeguard for a particular type of machinery or hazard zone, it shall be borne in mind that a fixed guard is simple and shall be used where access of an operator to the danger zone is not required during normal operation (operation without any malfunction) of the machinery.		P
	As the need for frequency of access increase this inevitably leads to the fixed guard not being replaced.		P
	This requires the use of an alternative protective measure (movable interlocking guard, sensitive protective equipment.)		P
	A combination of safeguards may sometimes be required. For example, where, in conjunction with a fixed guard, a mechanical loading (feeding) device is used to feed a workpiece into a machine, thereby removing the need for access to the primary hazard zone, a trip device may be required to protect against the secondary drawing-in or shearing hazard between the mechanical loading (feeding) device, when reachable, and the fixed guard.		P
	Consideration shall be given to the enclosure of control positions or intervention zones to provide combined protection against several hazards which may include:	_	P
	- hazards from falling or ejected objects (e.g. falling object protection structure)		P
	- emission hazards (e.g. protection against noise, vibration, radiation , harmful substances)		Р
	- hazards due to the environment (e.g. protection against heat, cold, foul weather)		P
	- hazards due to tipping over or rolling over of machinery (e.g. roll-over or tip-over protection structure)	No such hazards exist in this machine.	N
	The design of such enclosed work stations (e.g. cabs and cabins) shall take into account ergonomic principles concerning visibility, lighting, atmospheric conditions, access, posture.	stations.	N

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Clause	Requirement-Test	Result-Remark	Verdict
6.3.2.2	Where access to the hazard zone is not required during		P
	normal operation		
	Where access to the hazard zone is not required during		-
	normal operation of the machinery, safeguard should be		
	selected from the following:		
	a) fixed guard (see also ISO 14120)	Fixed guards are provided.	P
	b) interlocking guard with or without guard locking (see		N
	also 6.3.3.2.3, ISO 14119, ISO 14120);		
	c) self-closing guard (see ISO 14120:2002, 3.3.2)		P
	d) sensitive protective equipment, e.g. electro-sensitive	No sensitive	N
	protective equipment (see IEC 61496) or pressure sensitive mat (see ISO 13856)	protective equipment	
6.3.2.3	Where access to the hazard zone is required during		P
	normal operation		
	Where access to the hazard zone is required during		_
	normal operation of the machinery, safeguards should		
	be selected from the following:		
	a) interlocking guard with or without guard locking (see		N
	also ISO 14119, ISO 14120 and 6.3.3.2.3 of this		
	standard);		
	b) sensitive protective equipment, e.g electro-sensitive	No sensitive	N
	protective equipment (see IEC 61496)	protective equipment	
	c) adjustable guard;		N
	d) self-closing guard (see ISO 14120:2002, 3.3.2)		N
	e) two-hand control device (see ISO 13851)		N
	f) interlocking guard with a start function (control		N
	guard) (see 6.3.3.2.5 of this standard)		
6.3.2.4	Where access to the hazard zone is required for machine		P
	setting, teaching, process changeover, fault finding,		
	cleaning or maintenance.		
	As far as possible, machines shall be designed so that		P
	the safeguards provided for the protection of the		
	production operator may ensure also the protection of		
	personnel in charge of setting, teaching, process		
	changeover, fault finding, cleaning or maintenance		
	without hindering them in performing their task.		
	Such tasks shall be identified and considered in the risk		P

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Clause	Requirement-Test	Result-Remark	Verdict
	assessment as parts of the use of the machine (see 5.2)		
6.3.2.5	Selection and implementation of sensitive protective	No sensitive	N
	equipment	protective equipment	
6.3.2.5.1	Selection		N
	Due to the great diversity of the technologies on which		N
	their detection function is based, all types of sensitive		
	protective equipment are far from being equally suitable		
	for safety applications.		
	The following provisions are intended to provide the		N
	designer with criteria for selecting, for each		
	application, the most suitable device(s).		
	Types of sensitive protective equipment include, e.g.:		-
	- light curtains;		N
	- scanning devices as, e.g. laser scanners;		N
	- pressure sensitive mats;		N
	- trip bars, trip wires.		N
	Sensitive protective equipment can be used:		-
	- for tripping purposes;		N
	- for presence sensing;		N
	- for both tripping and presence sensing		N
	- to re-initiate machine operation, a practice which is		N
	subject to stringent conditions.		
	The following characteristics of the machinery, among		N
	others, can preclude the sole use of sensitive protective		
	equipment:		
	- tendency for the machinery to eject materials or		N
	component parts;		
	- necessity to guard against emissions (noise, radiation,		N
	dust, etc.)		
	- erratic or excessive machine stopping time;		N
	- inability of a machine to stop part-way through a cycle.		N
6.3.2.5.2	Implementation		N
	consideration should be given to:		-
	a) - size, characteristics and positioning of the		N
	detection zone (see ISO 13855, which deals with the		
	positioning of some types of sensitive protective		
	equipment)		
	b) - reaction of the device to fault conditions (see IEC		N

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Clause	Requirement-Test	Result-Remark	Verdict	
	,			
	61496for electro-sensitive protective equipment)			
	c)- possibility of circumvention		N	
	d)- detection capability and its variation over the course		N	
	of time (e.g. as a result of its susceptibility to different			
	environmental conditions such as the presence of			
	reflecting surfaces, other artificial light sources, sunlight			
	or impurities in the air.			
	sensitive protective equipment shall be integrated in the		N	
	operative part and associated with the control system of			
	the machine so that:			
	- a command is given as soon as a person or part of a		N	
	person is detected;			
	- the withdrawal of the person or part of a person		N	
	detected does not, by itself, restart the hazardous			
	machine function (s); therefore, the command given by			
	the sensitive protective equipment shall be maintained			
	by the control system until a new command is given;			
	- restarting the hazardous machine function(s) results		N	
	from the voluntary actuation, by the operator, of a			
	control device placed outside the hazard zone, where this			
	zone can be observed by the operator;			
1	- he machine cannot operate during interruption of the		N	
	detection function of the sensitive protective			
	equipment, except during muting phases,;			
	- the position and the shape of detection field		N	
	prevents, ,possibly together with fixed guards, a person			
	or part of a person from entering the hazard zone, or			
60070	being present in it, without being detected.			
6.3.2.5.3	Additional requirements for sensitive protective		N	
	equipment when used for cycle initiation.			
	In this exceptional application, starting of the machine		N	
	cycle is initiated by the withdrawal of a person or of the			
	detected part of a person from the sensing field of the			
	sensitive protective equipment, without any additional			
	start command, hence deviating from the general			
	requirement given in the second point of the dashed list			
	in 6.3.2.5.2, above. After switching on the power supply,			
	or when the machine has been stopped by the tripping			

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	function of the sensitive protective equipment, the		
	machine cycle shall be initiated only by voluntary		
	actuation of a start control.		
	Cycle initiation by sensitive protective equipment shall		-
	be subject to the following conditions:		
	a) only active optoelectronic protective devices		N
	(AOPDs) complying with IEC 61496 series shall be		
	used;		
	b) the requirements for an AOPD used as a tripping and		N
	presence-sensing device (see IEC 61496) are satisfied —		
	in particular, location, minimum distance (see ISO		
	13855), detection capability, reliability and monitoring		
	of control and braking systems;		
	c) the cycle time of the machine is short and the facility		N
	to re-initiate the machine upon clearing of the sensing		
	field is limited to a period commensurate with a single		
	normal cycle;		
	d) entering the sensing field of the AOPD(s) or opening		N
	interlocking guards is the only way to enter the hazard		
	zone;		
	e) if there is more than one AOPD safeguarding the		N
1	machine, only one of the AOPD (s) is capable of cycle		
	re-initiation;		
	f) with regard to the higher risk resulting from automatic		N
	cycle initiation, the AOPD and the associated control		
	system comply with a higher safety-related performance		
	than under normal conditions.		
6.3.2.6	Protective measures for stability		P
	If stability cannot be achieved by inherently safe design		P
	measures such as weight distribution (see 4.6), it will be		
	necessary to maintain it by protective measures such as		
	the use of:		
	- anchorage bolts;		P
	- locking devices;		P
	- movement limiters or mechanical stops;		N
	- acceleration or deceleration limiters;		N
	- load limiters;		N
	- alarms warning of the approach to stability or tipping		N

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Clause	Requirement-Test	Result-Remark	Verdict

	limits;	
6.3.2.7	Other protective devices	N
	When a machine requires continuous control by the	N
	operator(e.g. mobile machines, cranes) and an error of	
	the operator can generate a hazardous situation, this	
	machine shall be equipped with the necessary devices to	
	enable the operation to remain within specified limits,	
	in particular:	
	- when the operator has insufficient visibility of the	N
	hazard zone;	
	- when the operator lacks knowledge of the actual value	N
	of a safety -related parameter (e.ga distance, a speed,	
	the mass of a load, the angle of a slope)	
	- when hazards may result from operations other than	N
	those controlled by the operator;	
	The necessary devices include:	-
	- devices for limiting parameters of movement (distance,	N
	angle, velocity, acceleration)	
	- overloading and moment limiting devices:	N
	- devices to prevent collisions or interference with other	N
	machines;	
	-device for preventing hazards to pedestrian operators of	N
	mobile machinery or other pedestrians;	
	- torque limiting devices, breakage points to prevent	N
	excessive stress of components and assemblies;	
	- devices for limiting pressure, temperature;	N
	- devices for monitoring emissions;	N
	- devices prevent operation in the absence of the	N
	operator at the control position;	
	- device to prevent lifting operations unless stabilizers	N
	are in place;	
	- devices to limit inclination of the machine on a slope;	N
	- devices to ensure that components are in a safe position	N
	before traveling;	
	Automatic protective measures triggered by such	N
	devices which take operation of the machinery out of the	
	control of the operator (e.g. automatic stop of hazardous	
	movement) should be preceded or accompanied by a	

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	warning signal to enable the operator to take appropriate			
	action (see 6.4.3)			
6.3.3	Requirements for the design of guards and protective		P	
	devices			
6.3.3.1	General requirements		P	
	Guards and protective devices shall be designed to be	Guards and protective	P	
	suitable for the intended use, taking into account	devices have been		
	mechanical and other hazards involved. Guards and	appropriately		
	protective devices shall be compatible with the working			
	environment of the machine and designed so that they			
	cannot be easily defeated. They shall provide the			
	minimum possible interference with activities during			
	operation and other phases of machine life, in order to			
	reduce any incentive to defeat them.			
	Guards and protective devices shall:		-	
	- be of robust construction.	Steel	P	
	- not give rise to any additional hazard;	No additional hazard	P	
	- not be easy to by-pass or render non-operational;	not be easy to by-pass	P	
	- be located at an adequate distance from the danger	an adequate distance	P	
	zone (see ISO 13857 and ISO 13855).	from the danger zone		
	- cause minimum obstruction to the view of the		P	
	production process;			
	- enable essential work to be carried out on installation		P	
	and/or replacement of tools and also for maintenance by			
	allowing access only to the area where the work has to			
	be done, if possible without the guard or protective			
	device having to be moved;			
	For openings in the guards see ISO 13857		P	
6.3.3.2	Requirements for fixed guards		P	
6.3.3.2.1	Functions of guards		P	
	The functions that guards can achieve are:		P	
	- prevention of access to the space enclosed by guard	The space enclosed.	P	
	and/or	Containment of		
	- containment/capture of materials, workpieces, chips,			
	liquids which may be ejected or dropped by the	liquids which may be		
	machine and reduction of emissions(noise, radiation,	, .		
	hazardous substances such as dust, fumes, gases)	machine		
	which may be generated by the machine.			

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	Additionally, they may need to have particular	P
	propertied relating to electricity, temperature, fire,	
	explosion, vibration, visibility(see ISO 14120) and	
	operator position ergonomics(e.g. usability, operator's	
	movements, posture, repetitive movements).	
6.3.3.2.2	Requirements for fixed guards	P
	Fixed guards shall be securely held in place:	-
	- either permanently (e.g. by welding) All the fixed guards	P
	- or by means of fasteners (screws, nuts) making are securely held in	
	removal/opening impossible without using tools; they place by appropriate	
	should not remain closed without their fasteners (see fasteners.	
	ISO 14120)	
6.3.3.2.3	Requirements for movable guards	P
	a) movable guards which provide protection against	-
	hazards generated by moving transmission parts shall:	
	- as far as possible remain fixed to the machinery or by means of guides or	P
	other structure (generally by means of hinges or guides) hinges	
	when open;	
	- be interlocking guards (with guard locking when	N
	necessary) (see ISO 14119)	
	b) movable guards against hazards generated by	-
	non-transmission moving parts shall be designed and	
	associated with the machine control system so that:	
	- moving parts cannot start up while they are within the	N
	operator's reach and the operator cannot reach moving	
	parts once they have started up; this can be achieved by	
	interlocking guards, with guard locking when necessary.	
	- they can be adjusted only by an intentional action,	N
	such as the use of a tool or a key;	
	- the absence or failure of one of their components	N
	prevents starting of the moving parts or stops them; this	
	can be achieved by automatic monitoring (see 4.11.6)	
6.3.3.2.4	Requirements for adjustable guards	N
	Adjustable guards may only be used where the hazard	N
	zone cannot for operational reasons be completely	
	enclosed;	
	They shall:	-
	- be designed so that the adjustment remains fixed	N

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Clause	Requirement-Test	Result-Remark	Verdict
	during a given operation;		
	- be readily adjustable without the use of tools;		N
6.3.3.2.5	Requirements for interlocking guards with a start		N
	function (control guards)		
	An interlocking guard with a start function may be used		-
	provided that		
	- all requirements for interlocking guards are satisfied		N
	(see ISO 14119)		
	- the cycle time of the machine is short		N
	- the maximum opening time of the guard is present to a		N
	low value (e.g. equal to the cycle time). When this time		
	is exceeded, the hazardous function(s) cannot be		
	initiated by the closing of the interlocking guard with a		
	start function and resetting is necessary before restarting		
	the machine.		
	- the dimensions or shape of the machine do not allow a		N
	person, or part of a person, to stay in the hazard zone or		
	between the hazard zone and the guard while the guard		
	is closed (see ISO 14120)		
	- all other guards whether fixed (removable type) or		N
	movable are interlocking guards;		
	- the interlocking device associated with the interlocking		N
	guard with a start function is designed in such a way -		
	e.g. by duplication of position detectors and use of		
	automatic monitoring (see 4.11.6)- that its failure cannot		
	lead to an unintended/unexpected start-up;		
	- the guard is securely held open (e.g. by a spring or		N
	counterweight)such that it cannot initiate a start while		
	falling by its own weight;		
6.3.3.2.6	Hazards from guards		P
	Care shall be taken to prevent hazards which might be		-
	generated by :		
	- the guard construction (e.g. sharp edges or corners,	No harp edges and	P
	material);	corners.	
	- the movements of the guards (shearing or crushing		N
	zones generated by power-operated guards and by heavy		
6.2.2.5	guards which are liable to fall)		
6.3.3.3	Technical characteristics of protective devices		P

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Clause	Requirement-Test	Result-Remark	Verdict
	Protective devices shall be selected or designed and		P
	connected to the control system so as to ensure correct		
	implementation of their safety function (s) is ensured.		
	Protective devices shall be selected on the basis of their		P
	having met the appropriate product standard (for		
	example, IEC 61496 for active optoelectronic protective		
	devices) or shall be designed according to one or several		
	of the principles formulated in ISO 13849-1 or IEC		
	62061.		
	Protective devices shall be installed and connected to the		P
	control system so that they cannot be easily defeated.		
6.3.3.4	Provisions for alternative types of safeguards.		N
	Provisions should be made to facilitate the fitting of		N
	alternative types of safeguards on machinery where it s		
	known that this fitting will be necessary because the		
	work to be done on it will vary.		
6.3.4	Safeguarding for reducing emissions		P
6.3.4.1	General		
	If the measures for the reduction of emissions at source		P
	mentioned in 6.2.2.2 are not adequate, the machine shall		
	be provided with additional protective measures (see		
	6.3.4.2 to 6.3.4.5).		
6.3.4.2	Noise		P
	Additional protective measures include, for example:	Enclosures	P
	- enclosures (see ISO 15667)		
	- screens fitted to the machine;		
	- silencers (see ISO 14163)		
6.3.4.3	Vibration		N
	Additional protective measures include, for example,		N
	damping devices for vibration isolation between the		
	source and the exposed person such as resilient		
	mounting or suspended seats.		
	For measures for vibration isolation of stationary	,	N
	industrial machinery see EN 1299		
6.3.4.4	Hazardous substances		P
	Additional protective measures include, for example:		_
	- encapsulation of the machine (enclosure with negative	Encapsulation of the	P
	pressure);	machine	

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Clause	Requirement-Test	Result-Remark	Verdict
	- local exhaust ventilation with filtration.		N
	- wetting with liquids;		N
	- special ventilation in the area of the machine (air		N
	curtains, cabins for operators)		
6.3.4.5	Radiation		N
	Additional protective measures include, for example:		-
	- use of filtering and absorption;		N
	- use of attenuating screens or guards		N
6.3.5	Complementary protective measures		P
6.3.5.1	General		P
	Protective measures which are neither inherently safe		P
	design measures, nor safeguarding (implementation of		
	guards and/or protective devices), nor information for		
	use may have to be implemented as required by the		
	intended use and the reasonably foreseeable misuse of		
	the machine. Such measures include, but are not limited		
	to, the ones dealt with in 6.3.5.2 to 6.3.5.6		
6.3.5.2	Components and elements to achieve the emergency		P
	stop function		
	If following a risk assessment, a machine needs to be		-
	fitted with components and elements to achieve an		
	emergency stop function to enable actual or impending		
	emergency situations to be averted, the following		
	requirements apply:		
	- the actuators shall be clearly identifiable, clearly		P
	visible and readily accessible		
	- the hazardous process shall be stopped as quickly as		N
	possible without creating additional hazards . If this is		
	not possible or the risk cannot be reduced, it should be		
	questioned whether implementation of an emergency		
	stop function is the best solution;		
	- the emergency stop control shall trigger or permit the		P
	triggering of certain safeguard movements where		
	necessary.		
	Once active operation of the emergency stop device has		P
	ceased following an emergency stop command, the		1
	effect of this command shall be sustained until it is reset.		

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			1
	This reset shall be possible only at that location where		P
	the emergency stop command has been initiated. The		
	reset of the device shall not restart the machinery, but		
	only permit restarting.		
	More details for the design and selection of electrical		P
	components and elements to achieve the emergency stop		
	function are provided in EN 60204 series.		
6.3.5.3	Measures for the escape and rescue of trapped persons		P
	Measures for the escape and rescue of trapped persons		-
	may consist e.g. of:		
	- escape routes and shelters in installations generating		P
	operator-trapping hazards		
	- arrangements for moving some elements by hand, after		N
	an emergency stop		
	- arrangements for reversing the movement of some		N
	elements		
	- anchorage points for descender devices;		N
	- means of communication to enable trapped operators to		P
	call for help		
6.3.5.4	Measures for isolation and energy dissipation		P
	Especially with regard to their maintenance and repair,		P
1	machines shall be equipped with the technical means to		
	achieve the isolation from power supply(ies) and		
	dissipation of stored energy as a result of following		
	actions:		
	a) isolating (disconnecting, separating) the machine (or		P
	defined parts of the machine) from all power supplies;		
	b) locking (or otherwise securing) all the isolating units		P
	in the isolating position;		
	c) dissipating or , if this is not possible or practicable,		N
	restraining (containing) any stored energy which may		
	give rise to a hazard;		
	d) verifying, by means of a safe working procedure, that		P
	the actions taken according to a), b) and c) above have		
	produced the desired effect.		
	See ISO 14118:2000, clause 5 and EN 60204-1:2006, S	See the test report of	P
		EN 60204-1.	
6.3.5.5	Provisions for easy and safe handling of machines and		P

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Clause	Requirement-Test	Result-Remark	Verdict
	their heavy component parts		
	Machines and their component parts which cannot be		P
	moved or transported by hand shall be provided or		
	capable of being provided with suitable attachment	_	
	devices for transport by means of lifting gear.	by means of lifting	
		gear.	
	These attachments may be, among others,		-
	- standardized lifting appliances with slings, hooks,	slings	P
	eyebolts, or tapped holes for appliance fixing;		
	- appliances for automatic grabbing with a lifting hook		N
	when attachment is not possible from the ground.		
	- guiding grooves for machines to be transported by a fork truck;		N
	- lifting gear and appliances integrated into the machine.		N
	Parts of machinery which can be removed manually in	Not removed	N
	operation shall be provided with means for their safe	manually in operation	
	removal and replacement; See also 6.4.4c) (item 3).		
6.3.5.6	Measures for safe access to machinery		N
	Machinery shall be so designed as to enable operation	Comply with	P
	and all routine tasks relating to setting and/or	requirements	
	maintenance, to be carried out, as far as possible, by a		
1	person remaining at ground level.		
	Where this is not possible, machines shall have built-in		N
	platforms, stairs or other facilities to provide safe access		
	for those tasks, but care should be taken to ensure that		
	such platforms or stairs do not give access to danger		
	zones of machinery.		
	The walking areas shall be made from materials which	Comply with	P
	remain as slip resistant as practicable under working	requirements	
	conditions and, depending on the height from the		
	ground, suitable guard-rails (see ISO 14122-3) shall be		
	provided.		
	In large automated installations, particular attention shall		N
	be given to safe means of access such as walkways,		
	conveyor bridges or crossover points.		
	Means of access to parts of machinery located at a		N
	height shall be provided with collective means of		
	protection against falls (e.g. guard-rails for stairways,		

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	stepladders and platforms and/or safety cages for		
	ladders)		
	As necessary, anchorage points for personal protective		N
	equipment against falls from a height shall also be		
	provided (e.g. in carriers of machinery for lifting persons		
	or with elevating control sations)		
	Openings shall whenever possible open towards a safe		N
	position. They shall be designed to prevent hazards due		
	to unintended opening.		
	The necessary aids for access shall be provided (e.g.		N
	steps, handholds). Control devices shall be designed and		
	located to prevent their being used as aids for access.		
	When machinery for lifting goods and/or persons		P
	includes landings at fixed levels, these shall be equipped		
	with interlocking guards preventing falls when the		
	platform is not present at the level.		
	Movement of the lifting platform shall be prevented		P
	while the guards are open.		
	For detailed provisions see ISO 14122.		N
6.4	Information for use		P
6.4.1	General requirements		P
6.4.1.1	Drafting information for use is an integral part of the		P
	design of a machine (see figure 2).		
	Information of use consists of communication links,		P
	such as texts, words, signs, signals, symbols or		
	diagrams, used separately or in combination to convey		
	information to the user. It is directed to professional		
	and/or non-professional users.		
6.4.1.2	Information shall be provided to the user about the	See the instruction	P
	intended use of the machine, taking into account,		
	notably, all its operating modes.		
	The information shall contain all directions required to	See the instruction	P
	ensure safe and correct use of the machine. With this in		
	view, it shall inform and warn the user about residual		
	risk.		
	The information shall indicate, as appropriate,		-
	- the need for training,	See the instruction	P
	- the need for personal protective equipment,		P

- the possible need for additional guards or protective devices (see Figure 2, Footnote d). It shall not exclude uses of the machine that can reasonably be expected from its designation and description and shall also warn about the risk which would result from using the machine in other ways than the ones described in the information, especially considering its reasonably foresceable misuse. 6.4.1.3 Information for use shall cover, separately or incombination, transport, assembly and installation, commissioning, use of the machine (setting, teaching/programming or process changeover, operation, cleaning, fault-finding and maintenance) and, if necessary, dismantling, disabling and scrapping. 6.4.2 Location and nature of the information for use Depending on the risk, the time when the information is needed by the user and the machine design, it shall be decided whether the information — or parts thereof — are to be given: - in /on the machine itself (see 6.3 and 6.4.4) Adequate information — P is stated in the machine itself. - in accompanying documents (in particular instruction handbook, see 6.4.5) - on the packaging Adequate information — P is stated on the packaging Adequate information — P is stated on the packaging Adequate information — P Signals and warnings outside the machine. Standardized phrases shall be considered where important messages such as warnings need to be given (see also IEC 62079) 6.4.3 Signals and warning devices Visual signals (e.g. flashing lights) and audible signals (e.g. sirens) may be used to warn of an impending devices are provided. hazardous event such as machine start-up or overspeed. Such signals may also be used to warn the operator Please the related before the triggering of automatic protective measures clause.	EN ISO 12100:2010			
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			Please the related	P

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Clause	Requirement-Test	Result-Remark	Verdict	
	(see last paragraph of 5.2.7)			
	It is essential that these signals:		-	
	- be emitted before the occurrence of the hazardous	Unambiguous, clearly	P	
	event;	perceived, clearly		
	- be unambiguous;	recognized		
	- be clearly perceived and differentiated from all other			
	signals used;			
	- be clearly recognized by the operator and other			
	persons.			
	The warning devices shall be designed and located such		N	
	that checking is easy.			
	The information for use shall prescribe regular checking		P	
	of warning devices.			
	The attention of designers is drawn to the risks from		P	
	"sensorial saturation" which results from too many			
	visual and/or acoustic signals, which may also lead to			
	defeating the warning devices.			
6.4.4	Markings, signs (pictograms), written warnings		P	
	Machinery shall bear all markings which are necessary:		-	
	a) for its unambiguous identification, at least:		-	
	- name and address of the manufacturer;	Anhui Toploong CNC	P	
1	- designation of series or type;	Equipment Manufacturing		
	- serial number, if any.	Co., Ltd.		
		10 Hehuan Road,		
		High-tech Zone, Hefei City,		
		Anhui Province, China		
	b) in order to indicate its compliance with mandatory		N	
	requirements;			
	- marking;			
	- written indications (e.g. for machines intended for use			
	in potentially explosive atmosphere)			
	c) for its safe use, e.g.:		-	
	- maximum speed of rotating parts;		N	
	- maximum diameter of tools;		N	
	- mass (expressed in kilograms) of the machine itself		N	
	and/or of removable parts			
	- maximum working load;		N	
	-necessity of wearing personal protective equipment;		P	

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Clause	Requirement-Test	Result-Remark	Verdict
	- guard adjustment data;		P
	- frequency of inspection.	See the instruction	P
	Information printed directly on the machine should be	Permanent and	P
	permanent and remain legible throughout the expected	remain legible	
	life of the machine.		
	Signs or written warnings only saying "danger" shall not		P
	be used.		
	Markings, signs and written warnings shall be readily		P
	understandable and unambiguous, especially as regards		
	the part of the function(s) of the machine which they are		
	related to.		
	Readily understandable signs (pictograms) should be		P
	used in preference to written warnings.		
	Signs and pictograms should only be used if they are		P
	understood in the culture in which the machinery is to be		
	used.	A 11 .1 1 1 1	D.
	Markings shall comply with recognized standards (see		P
	ISO 2972, ISO 7000, particularly for pictograms,		
	symbols, colours) See EN 60204 series as regards		
6.4.5	marking of electrical equipment. Accompanying documents (in particular, instruction		P
0.4.3	handbook)		1
6.4.5.1	Contents		P
	The instruction handbook or other written instructions		_
	(e.g. on the packaging) shall contain among others:		
	a) information relating to transport, handling and storage	All the related	P
	of the machine e.g. :	information is stated	
	- storage conditions for the machine;	in the instruction	
	- dimensions, mass value(s), position of the centre (s) of	handbook	
	gravity;		
	- indications for handling (e.g. drawings indicating		
	application points for lifting equipment)		

b) information relating to installation and commissioning of the machine, e.g. - fixing/anchoring and vibration dampening requirements; - assembly and mounting conditions; - space needed for use and maintenance; - permissible environmental conditions (e.g. temperature, moisture, vibration, electromagnetic radiation); - instructions for connecting the machine to power supply (particularly about protection against electrical overloading); - advice about waste removal /disposal; - if necessary, recommendations about protective measures which have to be taken by the user; e.g. additional safeguards, safety distances, safety signs and signals. c) information relating to the machine itself, e.g.: - detailed description of the machine, its fittings, its guards and/or protective devices; - comprehensive range of applications for which the machine is intended, including prohibited usages, if any, taking into account variations of the original machine if appropriate diagrams; - data about noise and vibration generated by the machine, about radiation, gases, vapours, dust emitted by it, with reference to the measuring methods used technical documentation about electrical equipment - documents attesting that the machine complies with		EN ISO 12100:2010		
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- documents attesting that the machine complies with		- technical documentation about electrical equipment		
		- documents attesting that the machine complies with		
mandatory requirements;		mandatory requirements;		

	EN ISO 12100:2010		
Clause	Requirement-Test	Result-Remark	Verdict
	d) information relating to the use of the machine, e.g.		P
	about:	information is stated	
	- intended use;	in the instruction	
	- description of manual controls (actuators);	handbook	
	- setting and adjustment;		
	- modes and means for stopping		
	- risks which could not be eliminated by the protective		
	measures taken by the designer;		
	- particular risks which may be generated by certain		
	applications, by the use of certain fittings, and about		
	specific safeguards which are necessary for such		
	applications.		
	- reasonably foreseeable misuse and prohibited usages;		
	- fault identification and location, repair, and re-starting		
	after an intervention;		
	- personal protective equipment which need to be used		
	and training required.		
	e) information for maintenance e.g.	All the related	P
	- nature and frequency of inspections for safety		
	functions;	in the instruction	
	- instructions relating to maintenance operations which		
	require a definite technical knowledge or particular skills		
	and hence should be carried out exclusively by skilled		
	persons (e.g. maintenance staff, specialists)		
	- instructions relating to maintenance actions (e.g.		
	replacement of parts) which do not require specific		
	skills and hence may be carried out by users (e.g.		
	operators)		
	- drawings and diagrams enabling maintenance		
	personnel to carry out their task rationally	G 11 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
	,	See the instruction	P
	dismantling and disposal;	handbook	
	g) information for emergency situations, e.g.:		N
	- type of fire-fighting equipment to be used.		
	- warning about possible emission or leakage of harmful		
	substance(s), and if possible, indication of means to fight		
	their effects.	A11 /1 1 / 1	
	h) maintenance instructions provided for skilled persons		P
	(second dash in e))and maintenance instructions	information is stated	

being

prepared,

the

	EN ISO 12100:2010	
Clause	Requirement-Test Result-Remark	Verdict
	provided for unskilled persons (third dash in e)), that in the instruction	
	should appear clearly separated from each other. handbook	
6.4.5.2	Production of the instruction handbook	P
	a) type and size of print shall ensure the best possible Legibility.	P
	legibility. Safety warnings and/or cautions should be	
	emphasized the use of colours, symbols and/or large	
	print.	
	b) information for use shall be given in the language(s) English	P
	of the country in which the machine will be used for the	
	first time and in the original version.	
	If more than one language are to be used, each language	
	should be readily distinguished from the other(s), and	
	efforts should be made to keep the translated text and the	
	relevant illustration together.	
	c) whenever helpful to the understanding, text should be See the Instruction	P
	supplemented with written details enabling, for handbook.	
	instance, manual controls (actuators) to be located and	
	identified; they should not be separated from the	
	accompanying text and should follow sequential	
	operations.	
	d) consideration should be given to presenting See the Instruction	P
	information in tabular form where this will aid handbook.	
	understanding.	
	Tables should be adjacent to the relevant text.	
	e) the use of colours should be considered, particularly	N
	in relation to components requiring quick identification.	
	f) when information for use is lengthy, a table of	P
	contents and/or an index should be given.	
	g) safety-relevant instructions which involve immediate	P
	action should be provided in a form readily available to	
	the operator.	
6.4.5.3	Drafting and editing information for use	P
	a) relationship to model : the information shall clearly See the difference	P
	relate to the specific model of machine and, if necessary, between the models	
	other appropriate identification (for example, by serial	
	number).	
	b) communicate principles : when information for use is	P
İ		

communication

process

	EN ISO 12100:2010		
Clause	Requirement-Test	Result-Remark	Verdict
	"see-think-use" should be followed in order to achieve the maximum effect and should follow sequential operations. The questions "how?" and "why?" should be anticipated and the answers provided.		
	c) information for use shall be as simple and as brief as possible, and should be expressed in consistent terms and units with a clear explanation of unusual technical terms.		P
	d) when it is foreseen that a machine will be put to N non-professional use, the instructions should be written in a form that is readily understood by the non-professional users. If personal protective equipment is required for the safe use of the machine, clear advice should be given, e.g. on the packaging as well as on the machine, so that this information is prominently displayed at the point of sale.		N
	e) durability and availability of the documents: K documents giving instructions for use should be for produced in durable form (i.e. they should be able to survive frequent handling by the user). It may be useful to mark them "keep for future reference". Where information for use is kept in electronic form (e.g. CD, DVD, tape) information on safety-related issues that need immediate action shall always be backed up with a hand copy that is readily available.		P
7	Documentation of risk assessment and risk reduction		P
	The documentation shall demonstrate the procedure that has been followed and the results that have been achieved. This includes, when relevant, documentation of		-
	a) the machinery for which the risk assessment has been made (for example, specifications, limits, intended use);		P
	b) any relevant assumptions that have been made (loads, strengths, safety factors, etc.);		P
	c) the hazards and hazardous situations identified and the hazardous events considered in the risk assessment;		P
	d) the information on which risk assessment was based (see 5.2):		_

	EN ISO 12100:2010		
Clause	Requirement-Test	Result-Remark	Verdict
			·
	1) the data used and the sources (accident histories,		P
	experience gained from risk reduction applied to similar		
	machinery, etc.);		
	2) the uncertainty associated with the data used and its		P
	impact on the risk assessment;		
	e) the risk reduction objectives to be achieved by	,	P
	protective measures;		
	f) the protective measures implemented to eliminate	Warning sign and	P
	identified hazards or to reduce risk;	wear PPE	
	g) residual risks associated with the machinery;		P
	h) the result of the risk assessment (see Figure 1);	See the risk	P
		assessment report.	
	i) any forms completed during the risk assessment.		P
	Standards or other specifications used to select		P
	protective measures referred to in f) above should be		
	referenced.		

	EN 60204-1:2018		
Clause	Requirement-Test	Result-Remark	Verdict

1	Scope	
	This part of EN 60204 applies to the application of This machine is within t	this P
	electrical and electronic equipment and systems to scope.	
	machines not portable by hand while working.	
	Including a group of machines working higher level	
	system aspects	
	This part is applicable to the electrical equipment or	P
	parts of the electrical equipment that operate with	
	nominal supply voltages not exceeding 1000V for	
	alternating current and not exceeding 1500V for	
	direct current, and with nominal frequencies not	
	exceeding 200Hz	
2	Normative references	-
3	Definitions	-
4	General requirements	P
4.1	The risks associated with the hazards relevant to the See the risk assessm	ent P
	electrical equipment shall be assess as part of the report in detail.	
	overall requirements for risk assessment of the	
	machine	
4.2	Selection of equipment	P
	Electrical components and devices shall be suitable Suitable for their intended	ded P
	for their intended use and shall conform to relevant use	
	IEC standards where such exist	
4.3	Electrical supply	P
4.3.1	Electrical equipment to be designed for correct See below operation with conditions of mains power supply	P
4.3.2	Supply Voltage 380V	P
	Frequency: 50/60Hz	P
	Harmonics: <5% of the total r.m.s	P
	voltage	
	Voltage unbalance: <5% positive sequence	P
	Voltage interruption: Comply with requirement	nt P
	Voltage dips: Comply with requirement	nt P

EN 60204-1:2018			
Clause	Requirement-Test	Result-Remark	Verdict
4.3.3	DC Supplies Voltage:		N
	Voltage interruption		N
	Ripple (peak-peak):		N
4.3.4	Onboard power supply acc. to cl. 4.3.2 and 4.3.3	Not onboard power supply	N
4.4	Physical environment and operating conditions	See instruction	P
4.4.1	Electrical equipment to be suitable for use in physical environment and operating conditions		Р
4.4.2	Electromagnetic compatibility (EMC)		P
	Equipment not to generate electromagnetic disturbances above harmful levels: (applicable EMC-standard: EN 50081-2)		Р
	Equipment has adequate level of immunity to EMC: (applicable EMC-standards: EN 50082-2)	EN 61000-6-3	Р
4.4.3	Electrical equipment to be capable for correct operation at intended ambient air temperature		Р
4.4.4	Electrical equipment to be capable for correct operation at specified relative humidity:		P
4.4.5	Electrical equipment capable of operating correctly at altitudes up to 1000 m above m.s.l.	,	P
4.4.6	Electrical equipment shall be adequately protected against ingress of solid properties and liquids		P
4.4.7	Ionizing and non-ionizing radiation Electrical equipment subject to radiation, additional measures to be taken to avoid equipment malfunction	to ionizing and non-	
4.4.8	Undesirable effects of vibration, shock and bump avoided	The machine equips with cushion reduced vibration	P
4.5	Transportation and storage		P
	-2.5 °C to + 55 °C And short periods not exceeding	Comply with the	P

	EN 60204-1:2018		
Clause	Requirement-Test	Result-Remark	Verdict
	24 h at up to + 70° C	requirements	
4.6	Provisions for handling		P
	Heavy and bulky equipment shall be moved by	Appropriate equipments	P
	cranes or similar equipment	are provided.	
4.7	Installation and operation		P
	According to supplier's instructions	All the related information	P
		is stated in the instruction	
		manual.	
5	Incoming supply conductors terminations and	devices for disconnecting	P
	and switching off		
5.1	Incoming supply conductor terminations		P
	Single or multiple power supply	Single power supply.	P
	The supply conductors are terminated at the supply	Mains Switch used	P
	disconnection device if not, the separate terminals		
	shall be provided		
	If a neutral conductor is used, it shall be indicated	Labelled by Letter N	P
	clearly in the technical documentation		
	No connection between the protective bonding	No connection	P
	circuit and the neutral conductor		
	All terminals for the incoming supply connection	All terminals marked	P
	shall be identified clearly	correct label	
5.2	Terminal for connection to the external protective ea	rthing system	P
	Shall be in the vicinity of the associated phase		P
	conductor terminals		
	Cross-sectional area of the external protective		P
	copper conductor according to table 1		
	Marking of the external protective conductor with	'PE' is marked.	P
	the letters "PE"		
	Other protective terminals shall be marked with the	Ť	P
	symbol 🛓		
	All protective terminals shall be coloured by use of	9/001	P
	the bicolor combination	STOP STOP	
L			

	EN 60204-1:2018		
Clause	Requirement-Test	Result-Remark	Verdict
5.3	Supply disconnecting (isolating) device		P
5.3.1	General		-
	Shall disconnect (isolate) the electrical equipment of the machine from supply when required	Mains switch and used circuit breaker	P
	If two or more supply disconnecting devices are provided, protective interlocks shall be used		P
5.3.2	Type		-
	 a) Switch-disconnector according to en60947-3 b) A disconnector with auxiliary contact c) Circuit breaker according to EN 60947-2 d) any other switching device in accordance with an IEC product standard e) a plug/socket combination for a flexible cable supply. 		P
5.3.3	Requirements		P
	Have one OFF and one ON position only	On and off position	P
	Marked clearly with "I" and "O"	Marked with "O" and "I"	Р
	Have a reset(tripped) position between "O" and "I"		N
	Have an external operating means		P
	The handle should be Black or Grey		N
	Could be locked in the OFF position		P
	Disconnect all live conductors of its power supply circuit		P
	Sufficient breaking capacity		P
5.3.4	Operating handle		-
	Shall be easily accessible and located:0.6 m~1.9 m		P
5.3.5	Excepted circuits		-
	Following circuits not disconnect by supply disconnecting device:		-
	Lighting circuits during maintenance or repair		P
	Plug/socket outlets exclusively used for	No plug/socket outlets	N

	EN 60204-1:2018		
Clause	Requirement-Test	Result-Remark	Verdict

	maintenance or repair	
	Undervoltage protection circuits used for automatic No undervoltage protection tripping only at power supply failures circuits	N
	Circuits of equipment to remain normally energised for satisfactory operation	N
	Control circuits for interlocking purposes	P
	Circuits which are not disconnected by supply disconnecting device:	-
	Permanent warning labels placed in proximity of supply disconnectors	N
	Appropriate remark in maintenance manual	N
	Warning label in proximity of circuit concerned	N
	or wiring separated from other wiring	N
	Wiring of safety interlocking circuits installed with different colour of insulation.	N
5.4	Devices for switching off for prevention of unexpected start-up	P
	Means shall be provided to prevent inadvertent and / or mistaken closure of the disconnecting device	P
	Such devices appropriate and convenient for intended use	Р
	Suitable placed	P
	Readily identifiable Marking used	P
	Disconnecting devices acc. to cl. 5.3.2 used:	P
	Other disconnecting devices for the following situations only:	-
	- no significant dismantling of the machine	N
	- adjustments requiring a relatively short time	N
	No work at the electrical equipment of the machine except:	_

EN 60204-1:2018			
Clause	Requirement-Test	Result-Remark	Verdict
	- no hazard arising of electric shock or burn		N
	- switched-off status cannot be released due to maintenance work		N
	- work of minor nature		N
5.5	Devices provided for disconnecting electrical equipment	nent	P
	Supply-disconnecting device used	Circuit breaker used	P
	Disconnecting device provided for each separated part of the machine or partial machine where necessary		P
	Disconnectors, fuse links etc. used only in enclosed electrical operating areas	Used in operation areas	P
	Such disconnecting devices appropriate and convenient for intended use and	Appropriate and convenient for intended use	P
	Suitably located and	Location suitable	P
	readily identifiable to which part it serves and	Marking used	P
5.6	Provided with adequate means to prevent unauthorised, inadvertent and /or mistaken closing	Identification applied	P
	Devices acc. to cl. 5.4 and 5.5 provided with locking means	Circuit breaker is inside the metal enclosure which is opened using key by skilled person	P
	Other means of protection against unintended energising used for non-lockable disconnecting devices (for electrical operating areas only)	Warning message used.	P
	Locking device not necessary for plug/ socket outlet combinations, if located in a suitable manner and under immediate supervision of the person carrying out the work	No plug/ socket outlet combinations.	N
6	Protection against electric shock		P
6.1	General	See the relevant clauses.	P

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Clause	Requirement-Test	Result-Remark	Verdict
6.2	Protection against direct contact		P
6.2.1	General	2 4 1 4 1	- D
	Either 6.2.2 or 6.2.3 and, where applicable, 6.2.4	See the relevant clauses.	P
	shall be applied When the againment is leasted in places onen to all 7	This machine shall be	N
	When the equipment is located in places open to all persons, measures of either 6.2.3 or 6.2.2 with all		IN
	min. degree of protection against direct contactly	•	
		authorized persons.	
6.2.2	Protection by enclosures	aumorized persons.	P
	Min protection degree for live parts: IP2X or IPXXB		P
	Min. protection degree for top surface:IP4X or IPXXD		P
	Opening an enclosure shall only be possible unconditions:	der one of the following	-
a)	The use of a key or tool is necessary by skilled or instructed persons	Open the enclosure by using a key	P
	Min. protection degree for live parts on the inside of doors:IP1X or IPXXA		P
	live parts likely to be touched during resetting or adjustment with protection degree IP2X or IPXXB		P
b)	The disconnection of live parts inside the enclosure before the enclosure may be opened (Use of the supply disconnecting device)		N
	at door interlocking safety circuit, door will open only when main isolator is in open position		N
	For skilled persons a special device provided, to defeatfollowing conditions:	at interlocking circuit under	
	Special device or tool provided to permit skilled personal that:	ons to defeat the interlock pr	rovided
	- opening of disconnector possible at all times while interlock is defeated		N
	- upon closing the door, interlock is automatically restored		N

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Clause	Requirement-Test Result-Remark	Verdict
	If more than one door allows access to live parts, care must be taken, at implementation of this subclause	N
	All parts remaining live after switching off mains supply to be protected against direct contact with at least IP2X or IPXXB	Р
	Such parts marked with warning symbol acc. to cl.17.2	P
	Excepted from this requirement for marking are:	
	- Parts that can be live only due to connection to interlocking circuits, distinguished by colour as potentially live acc. to cl. 14.2.4	N
	- Terminals of supply disconnecting device when latter mounted alone in a separate enclosure	N
c)	Opening without the use of a key or a tool and without disconnection of live parts shall be possible only when the min. protection degree is IP2X or IPXXB	N
6.2.3	Protection by insulation of live parts	P
	Live parts shall be covered by insulation which can only be removed by destruction	P
	Such insulation shall withstand the mechanical, chemical, electrical and thermal stresses under normal service conditions	Р
6.2.4	Protection against residual voltages After disconnecting, any exposed conductive part having a residual voltage that shall be discharged to 60V or less within 5 seconds - 0V within 1s, comply with requirement	P
	where pins of plugs or similar devices after withdrawal are exposed, discharge time = 1s	N
	such conductors protected against direct contact by at least IP2X or IPXXB	N
	if above requirements cannot be achieved,	N

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Clause	Requirement-Test	Result-Remark	Verdict
	additional disconnecting devices or appropriate warning devices shall be applied. (see cl. 13.8.4)		
6.2.5	Protection by barriers		_
	For protection by barriers, see 412.2 of IEC		N
	60364-4-41		
6.2.6	Protection by placing out of reach or protection by obstacles		-
	For protection by placing out of reach see 412.4 of IEC 60364-4-41		N
	For protection by obstacles see 412.3 of IEC 60364-4-41		N
	For collector wire systems or collector bar systems with a degree of protection less than IP2X see 13.8.1		N
6.3	Protection against indirect contact		P
6.3.1	General		-
	For each circuit or part, at least one of the measures	See the following	P
	in accordance with 6.3.2 to 6.3.3 shall be applied	descriptions.	
6.3.2	Measure to prevent the occurrence of a hazardous touch voltage		P
6.3.2.1	General		-
6.3.2.2	use of class II electrical devices or apparatus (double insulation, reinforced insulation or by equivalent insulation acc. to EN 60536)	Double insulation	P
	use of switchgear and control gear assemblies with total insulation acc. to EN 60439-1		Р
	application of supplementary or reinforced insulation acc. to EN 60364-4-41, 413.2		P
6.3.2.3	Electrical separation of an individual circuit to prevent hazardous touch voltage acc. to EN 60364-4-41, cl. 413.5	Electrical clearance and creepage distance comply relevant requirements	P
6.3.3	Protection by automatic disconnection of supply		N
	a) Use of protective device for automatic cut-off in the event of an insulation failure in a TN – or TT-system		N

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Clause	Requirement-Test Result-R	emark	Verdict
	b) Use of earth fault detection device to initiate automatic disconnection in an IT-System.		N
	initiation of warning signal only in case of first occurrence of a fault permitted		N
6.4	Protection by the use of PELV		N
6.4.1	General requirements		-
	a) nominal voltage not to exceed 25 AC (r.m.s.) or 60 DC (ripple-free) or		N
	6VAC or 15VDC for all other cases		N
	b) one side of PELV- circuit or one point of source of supply to be connected to PE- circuit		N
	c) live parts of PELV- circuits to be electrically separated from other live circuits.		N
	Electrical separation equal as required for safety isolating transformers (see IEC 60742)		N
	d) conductors of each PELV circuit to be physically separated from those of any other circuit.		N
	If not practicable, insulation provisions acc. to cl. 14.1.3 shall be app	plied	
	e) plugs and socket outlets for PELV- circuits shall conform to follow requirements:	wing	
	plugs shall not be able to enter socket outlets of other voltage systems		N
	socket outlets shall not admit plugs of other voltage systems		N
6.4.2	Sources for PELV		N
	safety isolating transformers		N
	source of current providing a degree of safety, equivalent to safety isolating transformers		N
	electrochemical or other source, independent of		N

7.2.4

Control circuits

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Clause	Requirement-Test	Result-Remark	Verdict
	circuit with higher voltage		
	electronic power supply conforming to appropriate standards		N
7	Protection of equipment		P
7.1	General		-
7.2	Over current protection		P
7.2.1	Overcurrent protection device provided	Circuit breaker and fuse have overcurrent protection function	P
7.2.2	Supply conductors		P
	The supplier is not responsible for providing the over current device for the supply conductors		P
	Installation diagram with data necessary for selection of the over current protective device	Related information is stated in the installation diagram.	P
7.2.3	Power circuits		P
	All conductors shall be protected against over current (except earthed neutral conductor)	Circuit breaker have applied to live conductors but neutral earth conductor	P
	Cross-section area of neutral conductor	Cross section area for neutral equal to other phase conductor. No overcurrent for neutral conductor	P
	For neutral earth conductors with cross sections smaller than phase conductors, measures acc. to item b, cl 473.3.2.1 of IEC 60364-4-473 will apply		N
	For IT-systems use of neutral earth conductor (N) is not recommended. Nevertheless if an N-conductor is used, measures acc. to cl. 473.3.2.2 of IEC 60364-4-473 shall apply.		N

Conductors of control circuits directly connected to | Circuit breaker used

supply voltage and circuits feeding control voltage transformers protected against overcurrent acc. to P

P

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Clause	Requirement-Test	Result-Remark	Verdict
	1	I	
	cl. 7.2.3		
	Control circuits fed via transformers of which one	No winding of secondary	N
	end of secondary winding is connected to PE circuit, will require overcurrent protective device	connect to PE terminal	
	only in the other secondary conductor		
7.2.5	Socket outlets and their associated conductors		N
	Overcurrent protection devices for socket outlets	No socket outlets and	N
	provided for non-earthed live conductors of each	associated conductors	
7.2.6	circuit feeding such socket outlets Lighting circuits		N
7.2.0			
	All unearthed conductors of local lighting circuits protected by overcurrent protective devices		N
7.2.7	Transformers		N
	Transformers shall be protected against overcurrent	Not applicable	N
	in accordance with the manufacturer's instructions		
	Avoid unnecessary tripping due to overcurrent		N
	caused by magnetizing inrush currents		
	Avoid temperature rise of transformer winding in		N
	excess of its permitted of its insulation class of		
	transformer in case of short circuit at secondary terminals		
	Type and setting of overcurrent protective device		N
	acc. to recommendations of transformer		11
	manufacturer		
7.2.8	Location of over current protective device		P
	Overcurrent protective device located at point	Located at point where	P
	where conductor is connected to the supply	conductor is connected to	
		the supply	_
	Current carrying capacity of conductors at least equal to that required for electrical load	Comply with requirement	P
			D
	Each connecting conductor to overcurrent protective devices not longer than 3 meters	2m max.	P
	Protective devices not longer than 3 meters	1	

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Clause	Requirement-Test	Result-Remark	Verdict

	Conductor protected by enclosure or duct By enclosure	P
7.2.9	Over current protective devices	P
	Rated short-circuit breaking capacity at least equal to prospective fault current at point of installation	P
	Current other than those coming from supply side taken into account Comply with requirement	P
	Reduced breaking capacity is permitted, where another protective device is installed at supply side with the necessary breaking capacity	N
	Back-up protection carefully checked, no Comply with requirement destruction of conductor or overcurrent protective device may result	P
	Co-ordination with other protective devices in circuit required	N
	Overcurrent protective devices in power circuits Circuit breaker used include fuses and circuit breakers. Electronic current limiting devices may also be used in protected circuits	P
7.2.10	Rating and setting of over current protective devices	P
	Rated current of fuses or overcurrent setting of other protective devices selected as low as possible, but adequate for anticipated overcurrents.	P
	Settings of overcurrent protective devices (See appended table 4.2) appropriately listed in technical documentation	P
7.3	Overload protection of motors	P
	Overload protection for all motors provided for ratings of > 0.5 kW in continuous operation.	P
	Protective device may be omitted for motors which Can't be overloaded cannot be overloaded	P
	Overload protection achieved by current sensing or Ihermal protection used limiting devices or temperature sensors.	P

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Clause	Requirement-Test	Result-Remark	Verdict

	Current overload detection provided for each live Thermal protection used conductor except for neutral conductor	P
	For motors supplied by single phase AC or DC power supply, current detection in one non-earthed live conductor only is permitted	N
	If overload protection is achieved by switching-off Comply with requirement device, all live conductors cut from power supply except neutral conductor	P
	For special duty motors, appropriate protective devices are recommended	N
	For motors where cooling can be impaired, a built- in thermal protection is recommended	N
	Automatic restarting of motors prevented after Excessive temperature operation of overload protective device, to avoid reached, motors stop, and cause of a hazardous condition start the motor using a start-button located on operator area	P
7.4	Abnormal temperature protection	N
	Resistance heating or similar devices which cause excessive heat, equipped with suitable overtemperature detection	N
7.5	Protection against supply interruption or voltage reduction and subsequent restoration	P
	Undervoltage protection provided for applications where loss of supply or undervoltage causes a hazardous condition	N
	If interruption or reduction of supply voltage is allowed for a short period of time, delayed undervoltage protection provided.	N
	Undervoltage protection not impair any stopping control of the machine	P
	Upon restoration of supply voltage, automatic or	P

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Clause	Requirement-Test Result-Remark	Verdict
	unexpected restarting of machine prevented	
	Undervoltage protection to initiate appropriate control responses to ensure co-ordination the groups of machines working together	P
7.6	Motor over speed protection	P
	Overspeed protection provided where overspeeding causes a hazardous condition	P
	Overspeed protection initiates appropriate control Start machine only using response and prevents automatic restarting start button	P
7.7	Earth fault/residual current protection	P
	To reduce damage to equipment due to earth fault currents below detection level, earth fault/residual protect used	P
	Detection level for earth fault protection set as low as possible	P
7.8	Phase sequence protection	
	Where an incorrect sequence of the supply voltage can cause a hazardous condition or damage to the machine, protection shall be provided	N
7.9	Protection against over voltage due to lighting and to switching surges	P
	Protective devices for the suppression of Circuit breaker used overvoltages caused by lightning strikes or switching surges provided	P
	Devices for suppression of overvoltages due to Circuit breaker used lightning, connected at incoming terminals of the supply disconnecting device	P
	Devices for suppression of overvoltages due to Circuit breaker used switching surges connected across terminals of all equipment requiring such protection	P
8	Equipotential bonding	P
8.1	General	
8.2	Protective bonding circuit	P
8.2.1	General	-

Clause Requirement-Test Result-Remark	Verdict

	On mobile machines with on-board power supplies,	N
	it shall be connected to a protective bonding	11
	terminal to provide protection against electric shock	
	When a mobile machine is also capable of being Not movable machine	N
	connected to an external incoming supply, the	11
	protective bonding terminal shall be the connection	
	point for the external protective conductor	
	All parts of the protective bonding circuit shall be so designed that they are capable of withstanding	P
	so designed that they are capable of withstanding to instructions	1
	the highest thermal and mechanical stresses	
	Any structural part of the electrical equipment or of	Р
	the machine may be used as part of protective	1
	bonding circuit	
	If an IT distribution system is used, the machine	Р
	structure shall be sued as part of the protective	1
	bonding circuit in conjunction with an earth fault	
	supervision system	
8.2.2	Protective conductors	P
	Protective conductors shall be identified according See clause 14.2.2 in detail.	P
	to 14.2.2	
	Copper conductors should be used Copper used	P
	Where a conductors material other than copper is Only copper conductors are	N
	used, its electrical resistance per unit length shall used.	
	not exceed that of the allowable copper conductor	
	and such conductors shall not be less than 16 mm2	
	in cross-sectional area	
	The cross-sectional area of protective conductors	
	shall be determined according to the requirements	P
	of:	
	-543 of IEC 60364-5-54; or	
	-7.4.3.1.7 of IEC 60439-1, as appropriate	
	Relationship between cross-section area of phase	P
	conductor and PE acc. to table 1	
8.2.3	Continuity of the protective bonding circuit	P
	All exposed conductive parts shall be connected to	
	the protective bonding circuit	P
	bonding circuits	

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Clause	Requirement-Test	Result-Remark	Verdict
	In case of removal of parts of PE system, remaining parts not to be interrupted	If one part removed, protective continuity not interrupted	P
	Connection and bonding points shall be so designed that their current-carrying capacity is not impaired by mechanical, chemical, or electrochemical influence	Not impaired by mechanical chemical or	P
	Particular consideration should be given if enclosure consists of aluminium and its alloys		P
	Metal ducts of flexible or rigid construction and metallic cable sheathes shall not be used as protective bonding conductors	No metal ducts and cable armouring used as or connected to protective bonding circuits	P
	Where the electrical equipment is mounted on lids, doors, or cover plates, continuity of the protective bonding circuit shall be ensured and it is recommended that a protective conductor is used	No such electrical	N
	Continuity of protective conductor ensured at cables which are exposed to damage		N
8.2.4	Exclusion of switching devices from the protective b	onding circuit	P
	Protective bonding circuit not incorporate a switching-/overcurrent protective device nor a means for current detection	No switching devices or any other current protective devices	P
	Interruption of protective conductors permitted by links, intended to be opened by instructed/skilled persons for test or measurement purposes by using a tool		P
8.2.5	Parts that need not to be connected to the protective	bonding circuit	P
	Parts which cannot be touched on large surfaces or grasped by hand due to its small size (less than approx. 50 x 50 mm), small parts such as screws, rivets, nameplates or		P

P

are located in such way, that either contact with live

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Clause	Requirement-Test	Result-Remark	Verdict

	parts or an insulation failure is unlikely		
8.2.6	Protective conductor connecting points		P
	All protective conductors shall be terminated in	Please see the related clause.	P
	Shall have no other function and shall not be used to attach or connect appliances or parts	Only for earth connection	P
	Use of earthing symbol $\stackrel{\bot}{=}$	Earthing symbol is used.	P
	By the bicolor combination GREEN-AND-YELLOW	GREEN-AND-YELLOW	P
8.3	Functional bonding		P
	Protection against maloperation as a result of insulation failures can be achieved by connecting to a common conductor in accordance with 9.4.3.1.		P
	For recommendations regarding functional bonding to avoid maloperation due to electromagnetic disturbances, see 4.4.2.		P
8.4	Measures to limit the effects of high leakage current		N
	The effects of high leakage current can be restricted to the equipment having high leakage current by connection of that equipment to a dedicated supply transformer having separate windings.		N
9	Control circuits and control functions		P
9.1	Control circuits		P
9.1.1	Control circuit supply		P
	Transformers shall be used for supplying the control circuits		N
	If several transformers used, secondary voltages in phase		N
	DC- control circuits connected to PE circuit supplied from a separate winding of the control circuit transformer or supplied from another control circuit transformer	supplied by switching	N
	Transformers not mandatory for machines with a single motor starter and maximum of two control devices		N

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Clause	Requirement-Test	Result-Remark	Verdict
9.1.2	Control circuit voltages		P
	The nominal voltage shall not exceed 277 V when		N
	supplied from a transformer		
9.1.3	Protection		P
	Over current protection shall be provided according	Circuit breaker	P
	to /.2.4 and /.2.10	Chrain ordanor	
9.2	Control functions		P
9.2.1	Start functions		P
	Start functions shall operate by energizing the	Start function applied	P
	relevant circuit	11	_
9.2.2	Stop functions		P
	Category 0:	Power circuit breaker	P
	Stopping by immediate removal of power to		
	machine actuators		
	Cotton and I	"СТОР" 144 - п	D
	Category 1:	"STOP" button	P
	A controlled stop with power available to machine		
	actuators. Then removal of power when stop condition has been achieved.		
	condition has been achieved.		
	Category 2:	Not provided	N
	A controlled stop with power left available to		
	machine actuators		
9.2.3	Operating modes		P
	When hazardous conditions can arise from mode		N
	selection, such selection shall be prevented by		
	suitable means.	selection.	
	Mode selection by itself shall not initiate machine		P
	operation (A separate action by the operator shall be	operation.	
	required)		
	Safeguarding shall remain effective for all operating		P
	modes		
	Indication of the selected operating mode shall be provided	Indication is indication.	P
9.2.4	Suspension of safety functions and/or protective mea	asures	P
	Where it is necessary to suspend safety functions		-
	(for example for setting or maintenance purposes),		
	by:		

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Clause	Requirement-Test Result-Remark	Verdict
	-disabling all other operating (control) modes; and	P
	-other relevant means (see 4.11.9 of ISO	-
	12100-2:2003), that can include, for example, one	
	or more of the following:	
	-initiation of operation by a hold-to-run device or	N
	by a similar control device;	
	-a portable control station with an emergency stop	N
	device and, where appropriate, an enabling device.	
	Where a portable control station is in use, initiation	
	of motion shall only be possible from that control	
	station;	N.T.
	-a cableless control station with a device to initiate	N
	stop functions in accordance with 9.2.7.3 and,	
	where appropriate, an enabling device.	NI
	-limitation of the speed or the power of motion;	N
0.2.5	-limitation of the range of motion.	N
9.2.5	Operation Council	P
9.2.5.1	General The processors interlegies (see 0.2) shall be provided.	P
	The necessary interlocks (see 9.3) shall be provided for safe operation	N
	Measures shall be taken to prevent movement of the machine in an unintended manner after any stopping of the machine	t P
9.2.5.2	Start	P
	The start of an operation shall be possible only all the safeguards are in when all the safeguards are in place and functional (except described in 9.2.4)	n P
	Hold-to-run control shall be used for the others	N
	machines, as appropriate	
	Suitable interlocks shall be provided to secure	P
	correct sequential starting	
	The use of more than one control station to initiate a Only one control station start used.	is N
9.2.5.3	Stop	P
	Category 0, category 1 and/or category 2 stops shall Category 0 stops are be provided where indicated by the risk assessment provided. and the functional requirements of the machines	P

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Clause	Requirement-Test	Result-Remark	Verdict

	Stop functions shall override related start functions	Stop functions have priorities over start functions.	P
	Facilities provided for connection of protective devices / interlocks		P
	If such protective device/ interlock causes a machine stop, it may be necessary to send such condition to the logic of the control system (PLC)		P
	Resetting of stop function must not initiate any hazardous condition	No hazard	P
	Emergency operations (emergency stop, emergency switching off)		P
9.2.5.4.1	General		-
9.2.5.4.2	Emergency stop		P
	Shall function either as a category 0 stop or as a category 1 stop	Category 0 stop.	P
	The choice of the emergency stop shall be determined by the risk assessment of the machine		P
	Where a category 0 stop is used for emergency stop function, it shall have only hard-wired electromechanical components		P
	Emergency stop has priority over all other functions and over all modes of operation	Override all functions	P
	Power to machine actuators that can cause hazardous condition(s) removed as quickly as possible without creating other hazards		P
	Resetting must not initiate a restart	After reset manually, pressing start button then start machine	P
9.2.5.4.3	Emergency switching off	-	
	Functional aspects of emergency switching-off function are given in IEC 60364-4-46 and should be provided where:		N
	Protection against direct contact is achieved only by		N

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Clause	Requirement-Test	Result-Remark	Verdict

	placing out of reach or by obstacles	
	There is the possibility of other hazards or damage by electricity	N
	Emergency switching-off is accomplished by disconnecting incoming supply of the machine, effecting in a category 0 stop	N
	When a machine cannot tolerate a category 0 stop, other means of protection is to be provided so that emergency switching-off is not necessary	N
9.2.5.5	Monitoring of command actions	
	Movement or action of a machine or parts of it, that can result in a hazardous condition be monitored	P
	On manually controlled machines, operators to provide some monitoring	N
	Conditions expected to be unreasonable for Protective device for motor monitoring by the operator, require means to overspeed detection, overload detection, overcurrent dection used	P
9.2.6	Other control functions	N
9.2.6.1	Hold-to-run controls	N
	Hold-to run controls shall require continuous actuation of the control devices to achieve operation	N
9.2.6.2	Two-hand control	N
	Three types of two-hand control are available, the selection of which is determined by the assessment	N
9.2.6.3	Enabling device	N
	It shall be designed to allow motion when actuated in one position only (In any other position motion shall be stopped)	N
9.2.6.4	Combined start and stop controls	N
	Push-buttons and similar devices that, when No this kind of device has operated, alternately initiate and stop motion shall been used. only be used for functions which cannot result in a hazardous condition	N

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Clause	Requirement-Test	Result-Remark	Verdict
			1
9.2.7	Cableless control		_
9.2.7.1	General		-
	Means shall be provided to readily remove or disconnect the power supply of the operator control station		N
	Means shall be provided, as necessary, to prevent unauthorized use of the operator control station		N
	Each operator control station shall carry an unambiguous indication of which machine is intended to be controlled by that operator control station		N
9.2.7.2	Control limitation		-
	Measures shall be taken to prevent the machine from responding to signals other than those from the intended operator control station		N
	Where necessary, means shall be provided so that the machine can only be controlled from operator control station in one or more predetermined zones or locations		N
9.2.7.3	Stop		-
	Operator control stations shall include a separate and clearly identifiable means to initiate the stop function of the machine or of all the motions that can cause a hazardous condition		N
	The actuating means to initiate this stop function shall not be marked or labeled as an emergency stop device		N
	A machine which is equipped wit cableless control shall have a means of automatically initiating the stopping of the machine and of preventing a potentially hazardous operation		N
9.2.7.4	Use of more than one operator control station		N
	Where a machine has more than one operator control station, measures shall be taken to ensure that only one control station can be enabled at a given time		N
	An indication of which operator control station is in		N

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Clause	Requirement-Test	Result-Remark	Verdict
	control of the machine shall be provided at suitable		
	locations as determined by the risk assessment of		
	the machine		
9.2.7.5	Battery-powered operator control stations		-
	A variation in the battery voltage shall not cause a		N
	hazardous condition		
	If one or more potentially hazardous motions are		N
	controlled using a battery-powered operator control		
	station, a clear warning shall be given to the		
	operator when a variation in battery voltage exceeds		
	specified limits		
	Under those circumstances, the operator control		N
	station shall remain functional long enough to put		
	the machine into a non-hazardous condition		
9.3	Protective interlocks		-
9.3.1	Reclosing or resetting of an interlocking safeguard		N
	The reclosing or resetting of an interlocking		N
	safeguard shall not initiate machine motion or		
	operation		
9.3.2	Exceeding operating limits		N
	Where an operating limit (for example speed,		N
	pressure, position) can be exceeded leading to a		
	hazardous situation, means shall be provided to		
	detect when a predetermined limit(s) is exceeded		
	and initiate an appropriate control action.		
9.3.3	Operation of auxiliary functions		N
	The correct operation of auxiliary functions shall be		N
	checked by appropriate devices		
0.2.4	Use of appropriate interlocking		N
9.3.4	Interlocks between different operations and for contrary n	notions	N
	Interlocks of contactors, relays, etc. between		N
	different operations and for opposite motions,		
	interlocks against such incorrect operation provided		
	Devening contestons interleded in sections 4		λT
	Reversing contactors interlocked in such way, that		N
	in normal service no short circuit occurs during		
	switching operation		

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Clause	Requirement-Test	Result-Remark	Verdict
	Where, for safety or for continuous operation, certain functions on the machine are required to be interrelated, proper co-ordination ensured by suitable interlocks		N
	For a group of machines working together in a co-ordinated manner and having more than one controller, provisions made for co-ordination of this controller		N
	If a failure of a mechanical brake actuator can result that the brake, is applied when the associated machine actuator is energised and a hazardous condition results, interlocks be provided to switch off the machine actuator		N
9.3.5	Reverse current braking		N
	Reverse current braking on a motor, effective measures taken to avoid motor starting in opposite direction at end of breaking where that reversal causes a hazardous condition, damage to the machine or to the process	No reverse current braking used for AC rotating motor	N
	Control circuits arranged so, that rotation of a motor shaft, not to result in a hazardous condition		N
9.4	Control functions in the event of failure		P
9.4.1	General requirements		P
	Measures to reduce those risks include but are not limited to:		-
	protective devices on the machine, (e.g. interlocking guards, trip devices)	Circuit breaker have protection function	P
	protective interlocking of electrical circuit	Not used	N
	use of proven circuit techniques and components (see cl. 9.4.2.)	Conform to relevant IEC standards	P
	provision of partial or complete redundancy (see cl. 9.4.2.2) or diversity (see cl. 9.4.2.3)		N

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Clause	Requirement-Test	Result-Remark	Verdict	
	provision for functional tests (see cl. 9.4.2.4)	Comply with clause 19.6	P	
	single failures only are to be considered		P	
	Where memory retention is achieved for example, by battery power, measures shall be taken to prevent hazardous situations arising from failure or removal of the battery.	achieved.	N	
	Means shall be provided to prevent unauthorized or inadvertent memory alteration by, for example, requiring the use of a key, access code or tool.		P	
9.4.2	Measures to minimize risk in the event of failure		P	
9.4.2.1	Use of proven circuit techniques and components		P	
	bonding of control circuits to protective circuit for operational purposes (see cl. 9.4.3.1)		P	
	connection of control devices in accordance with cl. 9.1.4		P	
	stopping by de-energising (see cl. 9.2.2)		P	
	switching of all live conductors to device being controlled (see cl. 9.4.3.1)		P	
	use of switching devices having positive (or direct) opening operation (see IEC 60947-5-1)		P	
	circuit design to reduce possibility of failures causing undesirable operations		P	
9.4.2.2	Provisions of partial or complete redundancy		N	
	off-line redundancy for protective functions, effective only when operating function fails		N	
	where off-line redundancy is use, suitable measures taken, to ensure that those control circuits are available when required		N	
	on-line redundancy for normal operation		N	
9.4.2.3	Provision of diversity		N	

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Clause	Requirement-Test Result-Remark	Verdict
	Use of control circuits having different principles of operation or using different types of devices may reduce faults and failures. Examples include:	-
	Combination of normally open and normally closed contacts operated by interlocking guards	N
	Use of different types of circuit components in start button, stop button control circuit	P
	Combination of electromechanical and electronic circuits in redundant configurations	N
	Combination of electrical and non-electrical systems (e.g. mechanical, hydraulic, pneumatic) may perform redundant functions and provide diversity	N
9.4.2.4	Provision for functional tests	P
	Automatic functional test carried out by the control System Comply with clause 18.6	P
	Manual function tests by inspection Comply with clause 18.6	P
	Tests at start-up and at predetermined intervals or as Comply with clause 18.6	P
	Combination as appropriate (see cl.17.2 and 18.6) Comply with clause 18.6	P
9.4.3	Protection against maloperation due to earth faults, voltage interruptions and loss of circuit continuity	P
9.4.3.1	Earth faults	P
	Earth faults on any control circuit causes no No motion unintentional starting, potentially hazardous motions or prevent stopping of machine	P
	For fulfilment of this requirement, bonding to PE circuit connected to PE-circuit provided and correct connection of conductor devices ensured	P
	Control circuits fed from transformer and not control circuits connected connected to PE- circuit provided with an insulation to PE circuits monitoring device	N

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Clause	Requirement-Test	Result-Remark	Verdict

		1	
	Multi-pole control switches which interrupt all live conductors use for START or STOP functions, which could cause hazardous condition or damage to the machine, in the event of unintentional starting or failure to stop.	switches	N
9.4.3.2	Voltage interruptions		P
	Where a memory device is used, proper functioning	Any loss of memory can't	P
	in the event of power failure shall be ensured to	result in a hazardous	
	prevent any loss of memory that can result in a	condition.	
0.4.2.2	hazardous condition		D.
9.4.3.3	Loss of circuit continuity		P
	Where the loss of continuity of safety-related control circuits depending upon sliding contacts can	No sliding contact used	N
	result in hazardous condition, appropriate measures		
	shall be taken		
10	Operator interface and machine-mounted control	l devices	P
10.1	General		P
10.1.1	General device requirements		P
	As far as is practicable, those devices shall be selected, mounted, and identified or coded according to IEC 60073 and IEC 60447		P
10.1.2	Location and mounting		P
	Machine-mounted control devices readily accessible for service and maintenance and	Readily accessible for service and maintenance	P
	Mounted to minimize possibility of damage from activities such as material handling		P
	Actuators of hand-operated control devices selected	and installed as follows:	
	Mounted not less than 0.6 m above servicing level, and within easy reach for operator (normal working position)		Р
	Placed so that operator is not exposed to a hazardous situation when operating them	No hazard	P
	Possibility of inadvertent operation is minimised	Marking clearly	P

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Clause	Requirement-Test	Result-Remark	Verdict
10.1.3	Protection		P
	Degree of protection sufficient for expected use against:		-
	Effects of aggressive liquids, vapours or gases in environment of machine	See instruction for environment requirement	P
	Ingress of contaminants	See instruction for environment requirement	P
	Operator interface control devices have a minimum degree of protection against direct contact of IPXXD		P
10.1.4	Position sensors		N
	Position sensors shall not be damaged in the event of over travel		N
	Position sensors used in circuits with safety-related functions shall have positive opening operation or shall provide similar reliability		N
10.1.5	Portable and pendant control stations		N
	Portable and pendant control stations and their control devices shall be so selected and arranged as to minimize the possibility of inadvertent machine operations caused by shocks and vibrations		N
10.2	Push-buttons		P
10.2.1	Colors		
	Push-button actuators shall be color -coded according to table 2		P
10.2.2	Markings		
	Recommendation that pushbuttons are preferably marked directly on actuator with symbols acc. to table 3	Comply with requirements	P
10.3	Indicator lights and displays		P
10.3.1	Colours for indication lights: RED, YELLOW, GREEN, BLUE Colours for confirmation: GREEN and WHITE		P
10.3.2	Colors		P
	Color-coded according to table 4	Comply with requirements	P

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Clause	Requirement-Test	Result-Remark	Verdict

	(Unless otherwise agree between the supplier and	
	the user)	
10.3.3	Flashing lights and displays	P
	Flashing lights for further information may be used for following purposes:	-
	to attract attention or	P
	to request immediate action or	P
	to indicate a discrepancy between command and actual state or	P
	to indicate a change in process (flashing during transition)	P
	higher frequency of flashing lights (pulse/pause ratios) recommended for higher priority of information	P
10.4	Illuminated push-buttons	N
	Illuminated push-button actuators colour-coded acc. to tables 2 and 4	N
	WHITE colour shall be use, if it is difficult in assigning an appropriate colour	N
	RED colour shall be use, for emergency stop actuators, not depending upon illumination conditions (ON /OFF status) only	N
10.5	Rotary control devices	N
	Devices having a rotational member shall be mounted to prevent rotation of the stationary member (Friction alone shall not be sufficient)	N
10.6	Start devices	P
	Start devices use to initiate start functions or Common push button used movement of machine or elements designed and to initiate start functions or mounted such as to minimize inadvertent operation movement of machine	P
	Mushroom - type actuators use for two-hand control devices No two-hand control devices	N

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Clause	Requirement-Test	Result-Remark	Verdict
	l		
10.7	Devices for emergency stop		P
10.7.1	Location Devices for an appropriate star shall be used in	Te in mandiles annoughly	P
	Devices for emergency stop shall be readily accessible	It is readily accessible.	P
	Emergency stop devices shall be located at each operator control station and at other locations where the initiation of an emergency stop can be required		Р
10.7.2	Types		P
	Use of type - a push-button operated switch - a pull-cord operated switch - a pedal-operated switch without a mechanical guard	Push button with mushroom head used	P
	Shall be of the self-latching type and shall have positive opening operation	Have self-latching function and positive opening operation	P
10.7.3	Colour of actuators		P
	Actuators of emergency stop devices are coloured RED	Red used	P
	Background immediately around actuator is coloured YELLOW		P
10.7.4	Local operation of the supply disconnecting device to effect emergency switching off		N
	Supply disconnecting device may be locally operated to serve as function of emergency stop when:		-
	it is readily accessible to operator		N
	it is of type described in cl. 5.3.2 a), b) or c)		N
	Supply disconnecting device shall meet colour requirements of cl. 10.7.4		N
10.8	Emergency switching off devices		N
10.8.1	Location of emergency switching-off devices normally placed separate from operator control		N

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Clause	Requirement-Test	Result-Remark	Verdict

	station	
	Operator control station equipped with separate emergency stop device, since function effects a category 0 emergency stop	N
10.8.2	Types of emergency switching-off devices include: Push-button operated switch or	N
	Pull-cord operated switch	N
	Devices of self-latching type and ensure positive (or direct) opening operation	N
	Push-button operated switch in break-glass enclosure	N
10.8.3	Actuators of emergency switching-off devices are coloured RED	N
	Background immediately around actuator (push-button) coloured YELLOW	N
	Actuators of push-button operated emergency switching-off devices be of palm- or mushroom-head type	N
10.8.4	When supply disconnecting device is locally operated for emergency switching-off, it shall be readily accessible	N
	Supply disconnecting device locally operated for emergency switching-off, shall meet colour requirement acc. to cl. 10.8.3.	N
10.9	Enabling control device	N
	When an enabling control device is provided as a part of a system, it shall signal the enabling control to allow operation when actuated in one position only.	N
11	Control gear: location, mounting, and enclosures	P
11.1	General requirements	P
	All control gear located and mounted so, as to cover Accessilbe and able	P

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Clause	Requirement-Test	Result-Remark	Verdict
	the following points: facilitate accessibility and maintain ability		
	facilitate protection against external influences or operating conditions under which operation is intended		P
	facilitate easy access for operation and maintenance of the machine and its associated equipment	Easy access for operation and maintenance	P
11.2	Location and mounting		P
11.2.1	Accessibility and maintenance		P
	all control-gear components placed and oriented so, that identification is possible without moving them or the associated wiring	Fixed on machine	P
	Components checked for correct operation or possible replacement without dismantling other equipment or parts of the machine	Part list provided Components replacement according to detailed spec.	P
	Terminals not associated with control gear also to conform to this requirement		P
	Operation and maintenance of all control gear possible from front of cabinet	From front of cabient, operation and manintenance possible	Р
	Special tools for removal of electronic devices provided with the equipment	No special tools used	P
	Access for regular maintenance or adjustment to equipment, relevant devices located between 0.4m to 2.0 m above servicing level		Р
	Terminals located at least 0.2 m above servicing level and placed such, that conductors and cables can be easily connected		Р
	No devices mounted on doors, except those for operating, indicating, measuring and cooling purposes on normally removable access-covers of enclosure	doors	P

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Clause	Requirement-Test	Result-Remark	Verdict

	Plug-in type control devices belonging functionally No plug-in type control together, their association made clear by type devices (shape), marking or reference designation single or in combination (see cl. 14.4.5)	N
	Plug-in type control devices, that are handled No plug-in type control during normal operation, shall be designed with devices non-interchangeable characteristics, where lack of such facility can result in malfunctioning Use of plug/socket combinations shall be Not applicable.	N
	unobstructed access	
	Plug/socket combinations, handled during normal No plug/socket operation, shall be located and mounted so as to combination provide unobstructed access	N
	If test points are provided, they should be:	
		N
	mounted so as to provide unobstructed access	N
	clearly marked to correspond with the documentation (see cl. 18.3)	N
	adequately insulated	N
11.2.2	Physical separation or grouping	
	Non-electrical parts and devices, not directly Not in enclosure associated with the electrical equipment, not located within enclosures containing control gear	P
	Devices such as solenoid valves separated from other electrical equipment	P
	Control devices mounted at same location and connected to the main supply voltage, or to both main supply and control voltage, are grouped separately from those connected to control voltage only	P
	Terminals separated into groups for: power circuits Terminals separated for power circuits	P

11.4

Enclosures, doors and openings

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Clause	Requirement-Test	Result-Remark	Verdict
	associated control circuits or	Terminals separated for control circuits	P
	other control circuits, fed from external sources		N
	Terminal groups mounted adjacently, providing that each group is readily identified	Readily identification	P
	When arranging the location of devices, clearances and creepage distances specified for them shall be maintained, taking into account external influences or physical conditions of its environment		P
11.2.3	Heating effects		P
	Heat generating components shall be located so that the temperature of each component in the cicinity remains within the permitted limit		Р
11.3	Degrees of protection		P
	Protection of control gear against ingress of solid foreign objects and liquids shall be adequate. External influences under which the equipment is intended to operate is to be taken into account and is to be		P
	Its protection sufficient against dust, coolants and swarf		P
	Enclosures of control gear provide a degree of protection of at least IP20	IP22	Р
	Exceptions:		
	a) Where an electrical operating area is use as a protective enclosure for an appropriate degree of protection against ingress of solid bodies and liquids		P
	b) Where removable collectors on collector bar systems are use, and IP55 is not achieved but measures of cl. 6.2.5 are applied		N

P

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Clause	Requirement-Test	Result-Remark	Verdict

Enclosures to withstand mechanical, electrical a thermal stress as well as effects of humidity duri normal service		P
Fasteners for doors or covers of captive type	Hinges, lock used	P
Windows for viewing internally mounted indicati devices, made of material suitable to withsta mechanical stress and chemical attack	<u> </u>	N
Doors of enclosure not wider than 0,9 meter		P
Doors with vertical hinges	Vertical hinges used	P
Doors with opening angle of at least 95 °		P
Gaskets of doors, lids, covers and enclosures withstand the chemical effects of aggressive liquid vapours or gases use on the machine	Comply with requirement	P
Means use to maintain degree of protection of an covers that require opening or removed for operations.		_
be securely attached to either door, cover enclosure	or Securely attached to door	F
not deteriorate due to removal or replacement door or cover and so impair degree of protection	of	F
all openings in enclosure closed by supplier(ensuring degree of protection specified equipment	` '	F
openings for cable entries at enclosure to be easily re-opened on site	Rubber cushion used for hole on inside-enclosure	F
suitable opening in base of enclosure within to machine provided, as to enable drainage of moists due to condensation		F
no opening between enclosure containing electric		F

12.2

Conductors

	EN 60204-1:2018		
Clause	Requirement-Test	Result-Remark	Verdict
	lubricating or hydraulic fluids		
	holes in enclosure for mounting purposes not impair required degree of protection	Not impair required degree of protection	Р
	If equipment could attain a surface temperature suffiduring normal or abnormal operation:	cient to cause a risk of fire	-
	located within an enclosure, that can withstand, without risk of fire or harmful effect, the heat emitted by the equipment or		N
	mounted and located at sufficient distance from adjacent equipment, so as to allow safe dissipation of heat or		N
	otherwise screened by material that can withstand, without risk of fire or harmful effect, the heat emitted by the equipment		N
11.5	Access to control gear		
	Minimum dimensions of doors and corridors for access to electrical operating areas: at least 0.7 meter wide and 2.0 meter high		Р
	Doors open outwards	Open outwards	P
		Not provided	N
12	Conductors and cables		P
12.1	General requirements		P
	Conductors and cables selected so as to be suitable for operating conditions and external influences that are existing	Input cables and outer ground bonding conductors are supplied by user according to instructions	Р
	Requirements not applicable for integral wiring of assemblies, subassemblies and devices that are manufactured and tested acc. to their relevant standard	Conform to relevant IEC standards	Р

P

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Clause	Requirement-Test	Result-Remark	Verdict

	Conductors shall be of copper Copper.	P
	Conductors of any other material shall have a Only copper conductors are	P
	nominal cross-sectional area such that, carrying the used. same current, the max. temerparure shall not exceed the value given in table 5	
	If aluminium is used, the cross-sectional area shall Only copper conductors are be at least 16mm ² used.	P
	All conductors that are subject to frequent Comply with requirement movement shall have flexible stranding of class 5 or class 6 (see table C.4)	P
12.3	Insulation	P
	Types of insulation include: Polyvinyl chloride (PVC)	P
	Rubber, natural and synthetic	N
	Silicone rubber (SiR)	N
	Mineral	N
	Cross-linked Polyethylene (XLPE)	N
	Ethylene Propylene Rubber compound (EPR)	N
	Poly-Tetra-Fluor-Ethylene (PTFE)	N
	Where insulation of conductors or cables can constitute hazards due to propagation of fire or emission of toxic/ corrosive fumes, guidance from cable supplier to be sought	N
	Special attention to integrity of a circuit having a safety-related function	N
	Dielectric strength of insulation adequate for 2000V, no breakdown required test voltage with a min. of 2000VAC for cables operating with voltages >50V AC or >120 VDC	P
	For separate PELV circuits, dielectric strength adequate for test voltage of 500VAC for a duration of 5 minutes	N

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Clause	Requirement-Test	Result-Remark	Verdict

	Mechanical strength and thickness of insulation Not be damaged during such that, insulation cannot be damaged during cable laying or in operation cable laying or in operation	P
12.4	Current-carrying capacity in normal service	P
	The current-carrying capacity depends on several factors, for example insulation material, number of conductors in a cable, design (sheath), methods of installation, grouping and ambient temperature.	P
	Current-carrying capacities for PVC insulated wiring between enclosures and individual items of equipment under steady-state conditions according to values given in table 6	P
12.5	Conductor and cable voltage drop	P
	The voltage drop for conductors and cables shall not exceed 5% of the nominal voltage	P
12.6	Flexible cables	P
12.6.1	General	P
	Flexible cables shall have class 5 or class 6 conductors	P
	cables exposed to severe duties shall be of adequate construction to protect against:	-
	abrasion due to mechanical handling and dragging across rough surfaces	P
	kinking to operation without cable guides	P
	stress resulting from guide rollers and forced guiding, being wound and re-wound on cable drums	P
12.6.2	Mechanical rating	P
	Cable handling system of machine designed such, as to keep tensile stress of conductors as low as practicable during machine operation	P
	tensile stress for copper conductors not to exceed 15 N/mm² of copper cross section area	P
	where tensile stress of conductors is exceeding 15	N

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Clause	Requirement-Test	Result-Remark	Verdict
	NY 2 11 0 11 1		
	N/mm ² , cables of special design are use		
	maximum stress for flexible cables agreed with the cable manufacturer		P
12.6.3	Current-carry capacity of cables wound on drums		N
	Cables wound on drums selected such, as the maximum allowable conductor temperature is not exceeded	Not be wound on drums	N
	cables for circular cross-section area, installed on drums, max. current-currying capacity in free air as declared acc. to table 7		N
12.7	Collector wires, collector bars and slip-ring assemblic	es	P
12.7.1	Protection against direct contact		P
	They shall be installed or enclosed in such way, that machine, protection against direct contact is achieve the following protective measures:	•	
	protection by partial insulation of live parts		P
	protection by enclosure or barriers provide a degree of protection of at least IP2X		P
	horizontal top surfaces of barriers or enclosures which are readily accessible provide a degree of protection of at least IP4X		P
	if required degree of protection is not achieved, protection by placing live parts out of reach in combination with emergency switching-off acc. to cl. 9.2.5.4.3 applied		N
	collector wires and bares placed such and / or protected as to prevent contact, especially for unprotected wires and bars, with conductive items such as, cords of pull-cord switches, strain-relief devices and drive chains and		P
	prevent damage from a swinging load		P
12.7.2	Protective conductor circuit		P
	Where collector wires, collector bars and slip-ring		P

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Clause	Requirement-Test	Result-Remark	Verdict
	assemblies are installed as part of the protective		
	bonding circuit(PE), they shall not carry current in normal operation		
	The continuity of the protective conductor circuit using sliding contacts shall e ensured by taking appropriate measures	Not use sliding contacts	N
12.7.3	Protective conductor current collectors		N
	Protective conductors of current collectors have a shape or are designed such, so that they are not interchangeable with other current collectors of the sliding contact type		N
12.7.4	Removable current collectors with a disconnect function		N
	Shall be so designed that the protective conductor circuit is interrupted only after the live conductors have been disconnected, and the continuity of the protective conductor circuit is re-established before any live conductor is reconnected		N
12.7.5	Clearance in air		P
	Clearances between respective conductors and between adjacent systems of collector wires, bars, slip-ring assemblies and their current collectors designed for operation in pollution degree III conditions		P
12.7.6	Creepage distances		P
	Creepage distances between the respective conductors, between adjacent systems of conductor wires, conductor bars and slip-ring assemblies, and their current collectors shall be suitable for operation in the intended environment, for example open air (IEC 60664-1), inside buildings, protected by enclosures.		P
	In abnormally dusty, moist or corrosive environments apply:	s, following creepage distan	ces
	for unprotected collector wires, bars and slip-ring		N

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Clause	Requirement-Test	Result-Remark	Verdict
	assemblies equipped with insulators, the minimum creepage distance is 60 mm		
	for enclosed collector wires, insulated multipole collector bars and insulated individual collector bars, the minimum creepage distance is 30 mm		N
	gradual reduction of insulation values due to unfavourable ambient conditions regarded		N
12.7.7	Conductor system sectioning		P
	Suitable design measures taken, in order to prevent energisation of adjacent sections by current collectors themselves	<u> </u>	P
12.7.8	Construction and installation of collector wire, collector bar systems and slip-ring assemblies		P
	Collector wires, collector bar systems and slip-ring assemblies use for power circuits kept separately from those use for control circuit applications		P
	above systems capable of withstanding without damage to mechanical forces and thermal effects of short circuit currents		P
	removable covers to above systems, laid underground or under floor, designed that they cannot be opened by one person without the use of a tool		N
	collector bars which are installed in a common metal enclosure, the individual section of it bonded together and earthed at several points depending upon their length		P
	Metal covers of collector bars laid underground or under floor, bonded together end earthed		N
	Underground and under floor collector bar ducts have drainage facilities		N
13	Wiring practices		P
13.1	Connections and routing		P

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Clause	Requirement-Test	Result-Remark	Verdict
13.1.1	General requirements		P
	All connections shall be secured against accidental loosening	Fixed by screws	P
	The means of connection shall be suitable for the cross-sectional areas and neutral of the conductors being terminated	Fixed by screws	P
	The connection of two or more conductors to one terminal is permitted (only when the terminal is designed for that purpose)		
	One protective bonding circuit conductor shall be connected to one terminal connecting point	One conductor connected to one terminal.	P
	Soldered connections shall only be permitted if terminals are suitable for soldering	No soldered connection hass been taked.	N
	Terminals on terminal blocks shall be plainly identified to correspond with markings on the diagrams		
	The installation of flexible conduits and cables shall be such that liquids shall drain away from the fittings	-	N
	Means to retain stranded conductors together when terminating conductors at terminals/ devices provided		P
	Solder not use for that purpose	No solder used	N
	Shielded conductors terminated so, as to prevent fraying of strands and to permit easy disconnection		N
	Identification tags shall be legible, permanent, and appropriate for the physical environment	The tags are legible, permanent, and appropriate for the physical environment.	
	Terminal blocks shall be so mounted and wired, that the internal and external wiring does not cross over the terminals		Р
13.1.2	Conductor and cable runs		P
	Shall be run from terminal to terminal without splices or joints	All of them are run from terminal to terminal without splices or joints.	Р

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Clause	Requirement-Test	Result-Remark	Verdict

	If it is necessary to connect and disconnect cables sufficient extra length assemblies, a sufficient extra length shall be provided	P
	The terminations of cables shall be adequately Adequate support measure supported to prevent mechanical stresses at the has been taken. terminations of the conductors	P
	The protective conductor shall be placed close to the associated live conductors in order to decrease the impedance of the loop.	P
13.1.3	Conductors of different circuits	P
	Conductors of different circuits laid side by side Conductor for different and occupy the same duct or be in same circuits laid side by side or multiconductor cable, provided that such occupy the same duct arrangement does not impair proper functioning of respective circuits	P
	Where circuits operate at different voltage levels, Enough insulation conductors separated by suitable barriers or provided insulated for maximum voltage to which any conductor within the same duct is subjected	P
13.1.4	Connection between pick-up and pick-up converter of an inductive power supply system	P
	The cable between the pick-up and the pick-up converter as specified by the manufacturer of the inductive power supply shall be:	-
	as short as practicable;	P
	adequately protected against mechanical damage.	P
13.2	Identification of conductors	P
13.2.1	General requirements	P
	Conductors shall be identifiable at each termination Identification at each according to the technical documentation (see termination clause 17)	P
	Conductors are identified by number, alphanumeric, A combination of colour colour (either solid or with one or more stripes), or and numbers or alphanumeric.	P

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Clause	Requirement-Test	Result-Remark	Verdict

When numbers are used, they shall be Arabic; Arabic and Roman P		alphanumeric.	
13.2.2 Identification of the protective conductor Shall be really distinguishable by shape, location, marking or color When identification is by color alone, the bicolor combination GREEN-AND YELLOW shall be used for the bicolor combination GREEN-AND YELLOW shall be used on the protective conductor, the other color covering the remainder of the surface The color shall be Light Blue Participate			P
Shall be really distinguishable by shape, location, By marking and color. When identification is by color alone, the bicolor By combination GREEN-AND YELLOW shall be used GREEN-AND-YELLOW. For the bicolor combination GREEN-AND YELLOW: one of the color covers at least 30% and not more than 70% of the surface of the conductor, the other color covering the remainder of the surface. Use of graphical symbol		letters shall be Roman (either upper or lower case).	
marking or color When identification is by color alone, the bicolor By combination GREEN-AND YELLOW shall be used GREEN-AND-YELLOW: one of the color covers at least 30% and not more than 70% of the surface of the conductor, the other color covering the remainder of the surface Use of graphical symbol The earthing symbol has been used. Is.2.3 Identification of the neutral conductor The color shall be Light Blue Light BLUE must not be use for identification No other conductors use of any other conductor where confusion is possible Where bare conductors are use as neutral conductors and identification by colour is use, they either be coloured by LIGHT BLUE stripes, 15 to 100 mm wide in each compartment or unit, or at each accessible position Bare conductor colour coloured LIGHT BLUE over its full length Is.2.4 Identification by colour Identification of other conductors by colour, number, alphanumeric or a combination of colour and numbers or alphanumeric When numbers are use, they are in Arabic writing; letters are in Roman characters Provided Pro	13.2.2	Identification of the protective conductor	P
When identification is by color alone, the bicolor combination GREEN-AND YELLOW shall be used For the bicolor combination GREEN-AND YELLOW. For the bicolor combination GREEN-AND YELLOW. For the bicolor combination GREEN-AND YELLOW. For the bicolor conductor at least 30% and not more than 70% of the surface of the conductor, the other color covering the remainder of the surface Use of graphical symbol		Shall be really distinguishable by shape, location, By marking and color.	P
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13.3 Wiring inside enclosures P		When numbers are use, they are in Arabic writing;	P
		letters are in Roman characters	
	13.3	Wiring inside enclosures	P
Tranel Wiring sliphorted where necessary to keen ifflixed by screws		Panel wiring supported where necessary to keep it Fixed by screws	P

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Clause	Requirement-Test	Result-Remark	Verdict

	in place	
	Non-metallic ducts permitted only when they are of flame-retardant insulating material	N
	Electrical equipment mounted inside cabinets, designed to permit modification of wiring from front of cabinet (see cl. 11.2.1)	P
	Where that is not possible, access, doors or swing Doors provided out panels provided	P
	Connections to devices mounted on doors or to other movable parts made with flexible conductors (acc. to cl.13.2) to allow for frequent movement of those parts	N
	Conductors be anchored to the fixed part and the Fixed by screws and rubber movable part, independently of the electrical cushion anchor connection	P
	Conductors and cables that do not run in ducts are adequately supported	P
	Terminal blocks or plug /socket combinations use for control wiring, that extends beyond the enclosure Terminal blocks used for control wiring that extend beyond the enclosure	P
	Power cables and cables for measuring-circuits are directly connected to terminals of field located devices	P
13.4	Wiring outside enclosures	P
13.4.1	General requirements	P
	The protection degree shall be ensured when cables or ducts are introduced into the enclosure The protection degree can be secured.	P
13.4.2	External ducts -	
	Shall be enclosed in suitable ducts as described in 13.5 except for suitably protected cables Only power cord located outside of enclosure, provided by user according to instructions	P

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Clause	Requirement-Test	Result-Remark	Verdict
	Exempt from above requirements are suitably protected cables, installed without ducts and with or without use of open cable trays or cable supporting means		N
	Fittings used with ducts or multiconductor cable shall be suitable for the physical environment		P
	Flexible conduction or flexible multiconductor cable shall be used where it is necessary to employ flexible connections to pendant push-button stations		N
	The weight of the pendant stations shall be supported by means other that the flexible conduit or the flexible multiconductor cable		N
	Flexible conduit or flexible multiconductor cable shall be used for connections involving small or infrequent movements		N
13.4.3	Connection to moving elements of the machine		N
	Connection to frequently moving parts shall be made using conductors according to 12.2 and 12.6	Not used	N
	Flexible cable and flexible conduit shall be so installed as to avoid excess flexing and strainging, particularity t the fittings		N
	Cables subject to movement shall be supported in such a way that there is no mechanical strain on the connection points nor any sharp flexing		N
	If the requirement mentioned above is achieved by using of a loop, it shall have sufficient length to provide for a bending radius of the cable of at least 10 times the diameter of the cable		N
	Flexible cables of machines installed or protected in such way, as to minimise the possibility of external damage due to factors, that include the following cable use or potential abuse:		N
	being runned over by the machine itself		N
	being runned over by vehicles or other machines		N
	coming into contact with the machine structure		N

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Clause	Requirement-Test	Result-Remark	Verdict

	during movements	
	running in and out of cable baskets or, on / off cable drums	N
	acceleration and wind forces on festoon systems or suspended cables	N
	excessive rubbing by cable collector	N
	exposure to excessive radiated heat	N
	Cable sheath resistant to normal wear expected from normal movement and effects of atmospheric contaminants	N
	If cables subject to movement are close to moving parts, it shall have a space of at least 25 mm between the moving parts and the cables	N
	Where the distance mentioned above is not practicable, fixed barriers shall be provided between the cables and the moving parts	N
	The cable handing system shall be so designed that the lateral cable angles do no exceed 5°, avoiding torsion in the cable	N
	Measures shall be taken to ensure that at least two turns of flexible cables always remain on a drum	N
	Min. permitted bending radii for the forced guiding of flexible cables shall not less than the values given in table 8	N
	The strength section between section between two bends in an S-shaped length or a bend into another plane shall be at least 20 times the diameter of the cable	N
	Where flexible conduit is adjacent to moving parts, the construction and supporting means shall prevent damage to the flexile conduit under all conditions of operation	N
3.4.4	Interconnection of devices on the machine	P
	The connections shall be conveniently placed, adequately protected, and shown on the relevant	P

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Clause	Requirement-Test	Result-Remark	Verdict

	diagrams terminal used	
	Intermediate terminals are adequately protected	P
	Intermediate terminals are indicated on the wiring diagram	Р
	This enables easy access for testing purposes	P
13.4.5	Plug/socket combinations	N
	Where plug/socket combinations are provided, they No plug/socket shall fulfil one or more of the following combinations are provided. requirements as applicable:	N
	a) When installed correctly in accordance with f), plug/socket combinations shall be of such a type as to prevent unintentional contact with live parts at any time, including during insertion or removal of the connectors. The degree of protection shall be at least IPXXB. PELV circuits are excepted from this requirement.	N
	b) Have a first make last break protective bonding contact (earthing contact) (see also 6.3, 8.2.4) if used in TN- or TT-systems.	N
	c) Plug/socket combinations intended to be connected or disconnected during load conditions shall have sufficient load-breaking capacity. Where the plug/socket combination is rated at 30 A, or greater, it shall be interlocked with a switching device so that the connection and disconnection is possible only when the switching device is in the OFF position	N
	d) Plug/socket combinations that are rated at more than 16 A shall have a retaining means to prevent unintended or accidental disconnection.	N
	e) Where an unintended or accidental disconnection of plug/socket combinations can cause a hazardous situation, they shall have a retaining means.	N
	The installation of plug/socket combinations shall fulfil the following requirements as applicable:	N
	f) The component which remains live after	N

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Clause	Requirement-Test Result-Remark	Verdict		
	disconnection shall have a degree of protection of			
	at least IP2X or IPXXB, taking into account the			
	required clearance and creepage distances. PELV			
	circuits are excepted from this requirement.			
	g) Metallic housings of plug/socket combinations	N		
	shall be connected to the protective bonding circuit.			
	PELV circuits are excepted from this requirement.			
	h) Plug/socket combinations intended to carry	N		
	power loads but not to be disconnected during load			
	conditions shall have a retaining means to prevent			
	unintended or accidental disconnection and shall be			
	clearly marked that they are not intended to be			
	disconnected under load.	NI		
	i) Where more than one plug/socket combination	N		
	is provided in the same electrical equipment, the associated combinations shall be clearly			
	associated combinations shall be clearly identifiable. It is recommended that mechanical			
	coding be used to prevent incorrect insertion.			
	j) Plug/socket combinations used in control circuits	N		
	shall fulfil the applicable requirements of IEC	11		
	61984. Exception: see item k).			
	k) Plug/socket combinations intended for household	N		
	and similar general purposes shall not be used for	11		
	control circuits. In plug/socket combinations in			
	accordance with IEC 60309-1, only those contacts			
	shall be used for control circuits which are intended			
	for those purposes.			
13.4.6	Dismantling for shipment	P		
		n		
	If wiring needs to be disconnected for shipment, Internal wiring is located	P		
	terminals or plug/socket combinations are provided fully for shipment, and at the disconnecting points input terminal for power			
13.4.7	Additional conductors cords provided	P		
13.4./		P		
	Consideration should be given to providing Providing additional	r		
	additional conductors for maintenance or repair conductors for Spare conductors shall be connected to spare maintenance and repair.			
	terminals or isolated to prevent contact with live			
	terminals of isolated to prevent contact with five			

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Clause	Requirement-Test	Result-Remark	Verdict
	parts.		
13.5	Ducts, connection boxes and other boxes		P
13.5.1	General requirements		P
	Min. protection degree for ducts: IP 33		P
	All sharp edges, flash, burrs, rough surfaces or threads which the insulation of conductors may come into contact, removed from ducts and conduits		P
	In order to avoid confusion between conduits for electrical installation and those for oil, water or air, either physically separated or suitably identified		P

Ducts or cable trays mounted at least 2 meters Not for human passage

Ducts provided only for mechanical protection (see | Only for mechanical

protection

a No rigid metal conduit is

No rigid metal conduit is

N

N

P

N

P

P

P

N

N

N

N

N

Ducts or cable trays rigidly supported and

positioned at sufficient distance from moving parts

above the working surface in areas where human

Cable trays which are partially covered, not to serve

Conductors and cables suitable for installation in

The dimensions and arrangement of the ducts be

such as to facilitate the insertion of the conductors

galvanized

as cable trays or installation trunking

passage is required

cl. 8.2.3)

cable trays

and cables

Shall

Percentage fill of ducts

Rigid metal conduit and fittings

of

corrosion-resistant material

supported at each end Fitting shall be threaded

13.5.2

13.5.3

Where threadless fittings are used, the conduit shall No rigid metal conduit is

steel

of

used.

used.

or

Conduits shall be securely held in place and No rigid metal conduit is

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Clause	Requirement-Test	Result-Remark	Verdict

	be securely fastened to the equipment	used.	
	The conduit shall not be damage and the internal	No rigid metal conduit is	N
	diameter of the conduit shall not e effectively	used.	
	reduced when it is bent		
13.5.4	Flexible metal conduit and fittings		N
	Flexible metallic conduits and fittings consist of flexible metal tubing or wire mesh armour.	Not used flexible metallic conduits	N
	They are suitable for its application and environmental conditions	Not used flexible metallic conduits	N
13.5.5	Flexible non-metal conduit and fittings		P
	Flexible non-metallic conduits are resistant to buckling and with similar characteristics as the sheath of multicore cables		P
	They shall be suitable for its application and environmental conditions		P
	Joints and fittings compatible with conduits and appropriate for its application	Fixed by metal loop on machine	P
13.5.6	Cable trunking systems		
	Shall be rigidly supported and clear of all moving or		P
	contaminating portions of the machine	requirement	
	Covers shall be shaped to overlap the sides; gasket shall be permitted		P
	Covers shall be attached to cable trunking systems gy hinges or chain and held closed by means of captive screws or other suitable fasteners		P
	On horizontal cable trunking systems, the cover shall not be on the bottom	Comply with the requirement	P
	Where the cable trunking system is furnished in sections, the joints between sections shall fit tightly but need not be gasketed		P
	The only openings permitted shall be those required for wiring or for drainage		P
12 5 7	Cable trunking systems shall not have opened but unused knockouts	requirement	P
13.5.7	Machines compartments and cable trunking systems		

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Clause	Requirement-Test	Result-Remark	Verdict

		ı
13.5.8	The use of compartments or cable trunking systems within the column or base of a machine to enclose requirement conductors is permitted provided the compartments or cable trunking systems are isolated from coolant or oil reservoirs and are entirely enclosed. Conductors run in enclosed compartments and cable trunking systems shall be so secured and arranged that they are not subject to damage. Connection boxes and other boxes	P
	Cable connection boxes and junction boxes use for wiring purposes are readily accessible for maintenance (see cl. 11.3)	P
	They provide protection against ingress of solids or Enclosed metal enclosure liquids, taking into account external influences used except for hole for during operation of the machine (see cl. 11.3) external cable connection and openings for vent.	Р
	Junction boxes not have openings for cable entries Not used and are designed so, as to avoid ingress of entrained dust, lubricants and coolant	N
13.5.9	Motor connection boxes	P
	Shall enclose only connections to the motor and They enclose only connections to the motor and motor-mounted devices Shall enclose only connections to the motor and motor-mounted devices.	P
14	Electric motors and associated equipment	P
14.1	General requirements	P
	Electric motor should conform to the requirements of IEC 60034-1	P
	Electric motors and associated equipment protected against following risks:	-
	overcurrent (see cl. 7.2)	P
	thermal overload (see cl. 7.3)	P

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Clause	Requirement-Test Result-Remark	Verdict
	overspeed (see cl. 7.6)	P
	Compliance ensured with the requirements stated (see clauses 5.3, 5.4, 5.5, 7.5, 7.6 and 9.4)	P
	Motor control equipment shall be located and According to clause 11. mounted according to clause 11	P
14.2	Motor enclosures	P
	Selection of motor enclosure recommended acc. to Conform to EN 60034-5 EN 60034-5	P
	Degree of protection at least IP23	P
	Incorporated motors mounted such, as to provide adequate protection against mechanical damage	P
14.3	Motor dimensions	р
	Dimensions of motors conform to those given in IEC regulations and EN 60072-1 and EN 60072-2	P
14.4	Motor mounting and compartments	P
	Each motor with associated coupling, belt, pulley or chain mounted such, as to provide adequate protection and easy access for inspection, maintenance, adjustment or alignment, lubrication and replacement	P
	Motors mounted such, as to allow easy access to all terminal boxes	P
	Motors mounted such, as to ensure proper cooling Temperature rise to be within limits of relevant insulation class	P
	Temperature rise within limits of relevant insulation class	P
	If possible, motor compartments stay clean and dry and when required, ventilated directly to the outside of the machine	P

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Clause	Requirement-Test	Result-Remark	Verdict
	Motor-vents at an acceptable level and designed such, as to avoid ingress of swarf, dust or water spray		P
	No opening between motor compartment and any other compartment, which does not fulfil the requirement for motor compartments		P
14.5	Criteria for motor selection		P
	Electric motors selected acc. to service and environmental conditions		P
	Design criteria for evaluation include: type of motor and		P
	type of duty cycle (see IEC 60034-1) and	S1	P
	fixed speed or variable speed operation and	Variable speed operation	P
	mechanical vibrations and	Comply with requirement	P
	type of converter for motor speed control and		P
	influence of the harmonic spectrum of voltage and/or current when supplied from static converter on the temperature rise and		P
	method of starting and possible influence of inrush current		P
	variation of counter torque load with time and speed		P
	influence of loads with large inertia and		P
	influence of constant torque or constant power operation and		Р
	possible need of inductive reactors between motor and converter		P
14.6	Protective devices for mechanical brakes		P
	Operation of overload or overcurrent protective devices for mechanical brake-actuators initiate simultaneous de-energisation(release) of associated		P

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Clause	Requirement-Test	Result-Remark	Verdict

	machine actuators	
15	Accessories and lightning	N
15.1	Accessories	N
	Where the machine or its associated equipment is No provided with provided with socket-outlets for auxiliary socket-outlets equipment, the following will apply:	N
	the socket-outlets should conform to IEC 60309-1.	N
	if not possible, they are clearly marked with voltage and current ratings	N
	continuity of protective bonding circuit to be ensured	N
	all unearthed conductors connected to socket-outlets, protected against overcurrent	N
	when required, protection against overload in accordance with cl. 7.2 and cl. 7.3 separately from protection of other circuits	N
	if power supply to socket-outlets is not disconnected, than requirements of cl.5.3.5 apply	N
15.2	Local lighting of the machine and equipment	N
15.2.1	General	N
	Connections to the protective bonding circuit according to 8.2.2	N
	The ON-OFF switch shall not be incorporated in the lamp holder or in the flexible connecting cords	N
	Stroboscopic effects from lights shall be avoided	N
	Where fixed lighting is provided in an enclosure, No fixed lighting is electromagnetic compatibility should be taken into provided in an enclosure account using the principles outlined in 4.4.2.	N
15.2.2	Supply	N
	The nominal voltage of the local lighting circuit shall not exceed 250 V between conductors. A voltage not exceeding 50 V between conductors is recommended.	N

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Clause	Requirement-Test	Result-Remark	Verdict
	Lighting circuits supplied from one of the following sources:		-
	from a dedicated isolating transformer connected to load side, overcurrent protection provided in secondary circuit or		N
	a dedicated isolating transformer connected to line side provided, source permitted for maintenance purpose. lighting circuits placed in control enclosures only, overcurrent protection provided in secondary circuit or		N
	from a machine-circuit with dedicated overcurrent protection or		N
	an isolating transformer connected to the line side of the supply disconnecting device, provided with a dedicated primary disconnecting means (see 5.3.5) and secondary overcurrent protection, and mounted within the control enclosure adjacent to the supply disconnecting device (see also 13.1.3);		N
	an externally supplied lighting circuit (for example factory lighting supply).		N
15.2.3	Protection Protection		N
	Local lighting shall be protected according to 7.2.6		N
15.2.4	Fittings		N
	Adjustable lighting fittings shall be suitable for the physical environment		N
	The lamp holders shall be: According to the relevant IEC publication; Constructed with an insulating material protection the lamp cap so as to prevent unintended contact		N
	Reflectors shall be supported by a bracket and not by the lamp holder		N
16	Marking, warning signs and reference designation	as .	P
16.1	General		P

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Clause	Requirement-Test	Result-Remark	Verdict

	Warning signs, nameplates, markings, and Comply with requirement identification plates of sufficient durability to withstand the physical environment involved	P
16.2	Warning signs	P
16.2.1	Electric shock hazard	P
	Enclosures that do not otherwise clearly show that they contain electrical equipment that can give rise to a risk of electric shock shall be marked with the graphical symbol:	P
	The warning sign shall be plainly visible on the enclosure door or cover enclosure door.	P
	The warning sign may be omitted for:	-
	an enclosures equipped with a supply disconnecting device or	N
	an operator machine interface or for a control station or	P
	a single device with its own enclosure	N
16.2.2	Hot surfaces hazard	N
	Where the risk assessment shows the need to warn against the possibility of hazardous surface temperatures of the electrical equipment, the graphical symbol IEC 60417-5041 (DB:2002-10) shall be used.	N
16.3	Functional identification	P
	Control devices, visual indicators and displays use Marking clear and durable for man - machine interfaces clearly and durably marked with regard to their functions either on, or adjacent to it	P
	such markings as agreed between user and supplier	P
	preference given to the use of standard symbols	P
16.4	Marking of equipment	P

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Clause	Requirement-Test	Result-Remark	Verdict

	Equipment (for example controlgear assemblies) They have been marked	P
	shall be legibly and durably marked in a way that legibly and durably.	
	is plainly visible after the equipment is installed.	
	A nameplate giving the following information shall	-
	be attached to the enclosure adjacent to each	
	incoming supply:	
	name or trade mark of supplier; See the nameplate	P
	certification mark, when required; See the nameplate	P
	serial number, where applicable;	N
	rated voltage, number of phases and frequency (if See the nameplate	P
	a.c.), and full-load current for each supply;	
	short-circuit rating of the equipment; See the nameplate	P
	main document number (see IEC 62023).	N
	The full-load current shown on the nameplate shall See the nameplate	P
	be not less than the running currents for all motors	
	and other equipment that can be in operation at the	
	same time under normal conditions.	
	Where only a single motor controller is used, that	P
	information may instead be provided on the	
	machine nameplate where it is plainly visible.	
16.5	Reference designations -	
	All enclosures, assemblies, control devices, and	D
	components shall be plainly identified with the	P
	same reference designations as shown in the	
	technical documentation	
17	Technical documentation	P
17.1	General	P
	The information necessary for installation, All the information have	P
	operation, and maintenance of the electrical been provided by many	
	equipment of a machine shall be supplied in the forms in the instruction.	
	form of drawings, diagrams, charts, tales and	
	instructions	
	The information shall be in an agreed language In English.	P
	For very simple equipment, the relevant information	P
	may be contained in one document, provided that	
	the document shows all the devices of the electrical	
	equipment and enables the connections to the	

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Clause	se Requirement-Test Result-Remark					
17.2	supply network to be made. Information to be provided		P			
1,12	Information provided with electrical equipment shall include:					
	a) A main document (parts list or list of documents);		P			
	b) Complementary documents including:		-			
	1)a clear, comprehensive description of the equipment, installation and mounting, and the connection to the electrical supply(ies);		P			
	2) electrical supply(ies) requirements;	See instruction	P			
	3) Information about the physical environment	See instruction				
	4) Overview (block) diagram(s)	Provided by manufacturer	P			
	5) Circuit / wiring diagram(s)	Provided by manufacturer	P			
	6) information about:					
	- programming, as necessary for use of the equipment;		P			
	- Sequence of operation(s)	See instruction	P			
	-Frequency of inspection	See instruction	P			
	-Frequency and method of functional testing	See instruction	P			
	-Guidance on the adjustment, maintenance and repair, particularly of the protective devices and circuits	See instruction	P			
	-recommended spare parts list; and	See instruction	P			
	-list of tools supplied.	See instruction	P			
	7) Description of safeguards, interlocking functions and interlocking of separating safeguards for dangerous movements of co-ordinated operating machines		P			
	8) Description of safeguards and means provided	See instruction	P			

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	for applications with to suspend the safeguards	
	9) instructions on the procedures for securing the machine for safe maintenance; (see also 17.8);	Р
	10) information on handling, transportation and storage;	
	11) information regarding load currents, peak See instruction starting currents and permitted voltage drops, as applicable;	P
	12) information on the residual risks due to the See instruction protection measures adopted, indication of whether any particular training is required and specification of any necessary personal protective equipment.	Р
17.3	Requirements applicable to all documentation	
	Unless otherwise agreed between manufacturer and user:	-
	the documentation shall be in accordance with Comply with requirements relevant parts of IEC 61082;	P
	reference designations shall be in accordance with Comply with requirements relevant parts of IEC 61346;	P
	instructions/manuals shall be in accordance with Comply with requirements IEC 62079.	Р
	parts lists where provided shall be in accordance Comply with requirements with IEC 62027, class B.	Р
	For referencing of the different documents, the supplier shall select one of the following methods:	-
	-where the documentation consists of a small number of documents (for example less than 5) each of the documents shall carry as a cross-reference the document numbers of all other documents belonging to the electrical equipment; or	N
	-for single level main documents only (see IEC 62023), all documents shall be listed with document numbers and titles in a drawing or document list; or	P
	-all documents of a certain level (see IEC 62023) of the document structure shall be listed, with	N

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Clause	Requirement-Test	Result-Remark	Verdict			
	document numbers and titles, in a parts list belonging to the same level.					
17.4	Installation documents		P			
	The installation documents shall give all See instruction information necessary for the preliminary work of setting up the machine (including commissioning). In complex cases, it may be necessary to refer to the assembly drawings for details.					
	The recommended position, type, and cross-sectional areas of the supply cables to be installed on site shall be clearly indicated.	See instruction	P			
	The data necessary for choosing the type, characteristics, rated currents, and setting of the overcurrent protective device(s) for the supply conductors to the electrical equipment of the machine shall be stated (see 7.2.2).		P			
	Where necessary, the size, purpose, and location of any ducts in the foundation that are to be provided by the user shall be detailed (see Annex B).		N			
	The size, type, and purpose of ducts, cable trays, or cable supports between the machine and the associated equipment that are to be provided by the user shall be detailed (see Annex B).		P			
	Where necessary, the diagram shall indicate where space is required for the removal or servicing of the electrical equipment.		P			
	In addition, where it is appropriate, an interconnection diagram or table shall be provided. That diagram or table shall give full information about all external connections.		P			
	Where the electrical equipment is intended to be operated from more than one source of electrical supply, the interconnection diagram or table shall indicate the modifications or interconnections required for the use of each supply.		N			
17.5	Overview diagrams and function diagrams		P			
	Where it is necessary to facilitate the understanding	See instruction	P			

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Clause	Requirement-Test Result-Remark			
	of the principles of operation, an overview diagram shall be provided.			
	An overview diagram symbolically represents the electrical equipment together with its functional interrelationships without necessarily showing all of the interconnections.		P	
	Function diagrams may be provided as either part of, or in addition to, the overview diagram.	See instruction	P	
17.6	Circuit diagrams		P	
	Circuit diagrams show the electrical circuits on the machine and its associated electrical equipment		P	
	Any graphical symbol not shown in EN 60617 and EN 60417-1 must be separately shown and described on the wiring diagrams or supporting		P	
	documents The symbols and identification of components consistent throughout all documents and on the machine	See circuit diagram	P	
	Where appropriate, a diagram provided, showing the interface terminals and connections	See circuit diagram	P	
	The diagram shows a reference to the detailed circuit diagram of each unit	See circuit diagram	P	
	Switch symbols shown on the circuit diagrams with all supplies turned off and with the machine and its electrical equipment in normal starting condition	See circuit diagram	P	
	Conductors identified acc. to cl.13.2	See circuit diagram	P	
	Characteristics relating to the function of the control device and components which are not evident from their symbolic representation, included on the diagrams adjacent to the symbol or referenced to a footnote		P	
17.7	Operating manual Technical documentation containing an operating manual, outlining proper procedures for set-up and use of equipment	See instruction	P	

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Clause	Requirement-Test	Result-Remark	Verdict	
	Particular attention given to safety measures provided and the improper methods of operation, that are anticipated	See instruction	P	
	Detailed information provided on methods for equipment programming, program verification and additional safety procedures		N	
17.8	Maintenance manual	-		
	Technical documentation to contain a maintenance manual, detailing proper procedures for adjustment, servicing or preventive inspection and repair	See instruction	Р	
	Recommendations regarding maintenance or service records are part of it	See instruction	Р	
	Methods for the verification of proper operation provided	See instruction	P	
17.9	Parts list	-		
	The spare parts list comprises as a minimum information for ordering of spares or replacement of parts which are required for preventive or corrective maintenance and recommended spares	-	Р	
18	Verification		P	
18.1	General			
	This part of IEC 60204 gives general requirements for the electrical equipment of machines.		P	
	The extent of verification will be given in the dedicated product standard for a particular machine. Where there is no dedicated product standard for the machine, the verifications shall always include the items a), b) and f) and may include one or more of the items c) to e):		-	
	a) verification that the electrical equipment complies with its technical documentation;		P	
	b) in case of protection against indirect contact by automatic disconnection, conditions for protection by automatic disconnection shall be verified according to 18.2;		P	
	c) insulation resistance test (see 18.3);		P	
	d) voltage test (see 18.4);		P	

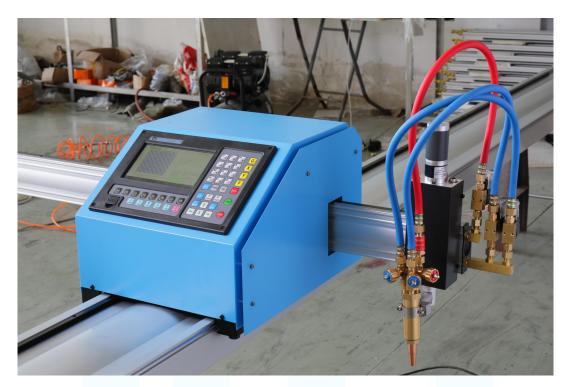
	EN 60204-1:2018					
Clause	use Requirement-Test Result-Remark					
	e) protection against residual voltage (see 18.5);		P			
	f) functional tests (see 18.6).		P			
	When these tests are performed, it is recommended					
	that they follow the sequence listed above.					
18.2	Verification of conditions for protection by automatic	c disconnection of supply	P			
18.2.1	General		P			
	The conditions for automatic disconnection of		P			
	supply (see 6.3.3) shall be verified by tests.					
	For TN-systems, those test methods are described in		P			
	18.2.2; their application for different conditions of					
	supply are specified in 18.2.3.					
	For TT and IT systems, see IEC 60364-6-61.		N			
18.2.2	Test methods in TN-systems		N			
18.2.3	Application of the test methods for TN-systems					
18.3	Insulation resistance tests		P			
	Insulation resistance measured with 500VDC (See appended table 18.3)					
	between power circuit conductors and PE-circuit is					
	to be =1.0 M Ω					
	Insulation value must be = $1.0 \text{ M}\Omega$	(See appended table 18.3)	P			
	Test made on individual sections of complete	(Caraman da da la la 10.2)	D			
	electrical installation	(See appended table 18.3)	P			
	For certain parts of the electrical equipment, a lower		N			
	minimum insulation value is permitted, but not less		N			
	than 50 k Ω					
18.4	Voltage tests		P			
	Test conditions:	1000 V, 1min not	P			
	at least 1 second	breakdown.				
	test voltage is twice the raged supply					
	voltage of the equipment or 1000 V, whichever is					
	greater					
	frequency of 50/60 Hz					
	supplied from a transformer with a min. rating of					
	500 VA shall not breakdown					
18.5	Protection against residual voltages		N			
	Tests shall be preformed to ensure complacence		N			
	with 6.2.4					
18.6	Functional test		P			

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Clause	Clause Requirement-Test Result-Remark					
	The functions of electrical equipment shall be tested (See appended table 18.6)					
	(particularly those related to safety and					
	safeguarding)					
18.7	Retesting	N				
	Where a portion of the machine and its associated	N				
	equipment is changed or modified, that portion shall					
	ere verified and retested, as is appropriate					

Equipment sheet of electrical safety test

No.	Name	Туре	Serial No.	Valid calibration date	Used
1	Vernier callipers	0~150mm	KJ050	2020-08-21~2021-08-20	√
2	Test finger		KS048	2020-09-14~2021-09-13	$\sqrt{}$
3	Micrometer callipers	25~50mm	MJ003	2020-03-23~2021-03-22	√
4	Digital multimeter	1587(Fluke)	MJ035	2020-08-21~2021-08-20	√
5	Grounding resistance measurement instrument	PC39A	KJ065	2020-05-21~2021-05-20	V
6	High voltage withstand tester	CS2672B	KJ054	2020-08-09~2021-08-08	√

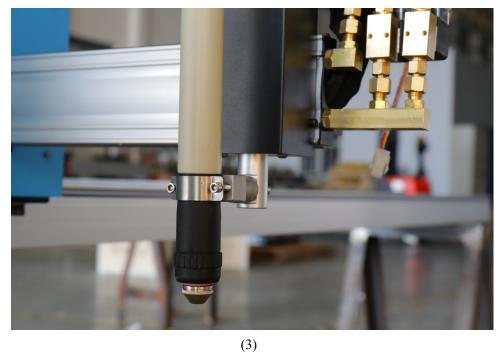
Product picture:



(1)



(2)





Technical Construction File

File No.: JAT-CE2292-0277

Revision Date: 2020/10/20

Applicant/Holder: Anhui Toploong CNC Equipment Manufacturing Co., Ltd.

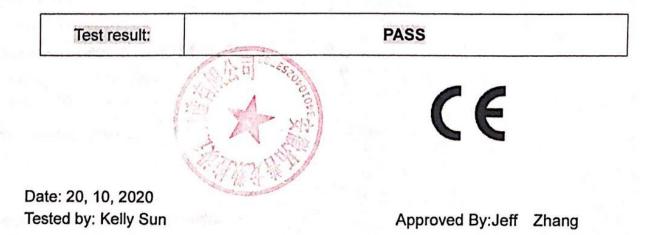
Address: 10 Hehuan Road, High-tech Zone, Hefei City, Anhui Province, China

Manufacturer: Anhui Toploong CNC Equipment Manufacturing Co., Ltd.

Product Type: Portable Flame and Plasma CNC Cutting Machine

Models:ZL1630

According to : MD 2006/42/EC



The End